

Dehn surgery along the Mazur link and Akbulut-Yasui links

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The 11th East Asian School of Knots and Related Topics

Osaka City University

- 1 Intro.
- 2 The Mazur Link and the Akbulut-Yasui Link
- 3 Using Martelli-Petronio-Roukema's results

A Framed link describes **3-dim** and **4-dim** manifolds.

Lens space $L(p, q)$

$$\frac{p}{q} = a_1 - \frac{1}{a_2 - \frac{1}{a_3 - \dots - \frac{1}{a_n}}} \quad (a_i > 1)$$

$$-\frac{p}{q} \bigcirc = \overset{-a_1}{\bigcirc} \overset{-a_2}{\bigcirc} \overset{-a_3}{\bigcirc} \dots \overset{-a_n}{\bigcirc}$$

ex. $L(19, 12)$
 $-L(19, 7)$

$$\frac{19}{12} = 2 - \frac{1}{\frac{12}{5}} = 2 - \frac{1}{3 - \frac{1}{2 - \frac{1}{3}}} \quad \overset{-2}{\bigcirc} \overset{-3}{\bigcirc} \overset{-2}{\bigcirc} \overset{-3}{\bigcirc}$$

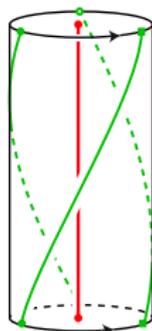
Seifert manifold : 3-manifolds that admit S^1 -action without fixed points

Classified by the base surface Σ , obstruction $b \in \mathbb{Z}$ and the singular fibers $\{(\alpha_i, \beta_i)\}$ (coprime pairs)

Today's Notation $\Sigma(b; (\alpha_1, \beta_1), (\alpha_2, \beta_2), \dots, (\alpha_n, \beta_n))$

- $\Sigma = S(S^2)$, D a disk, or A an annulus.
- Identification b is omitted if $b = 0$.

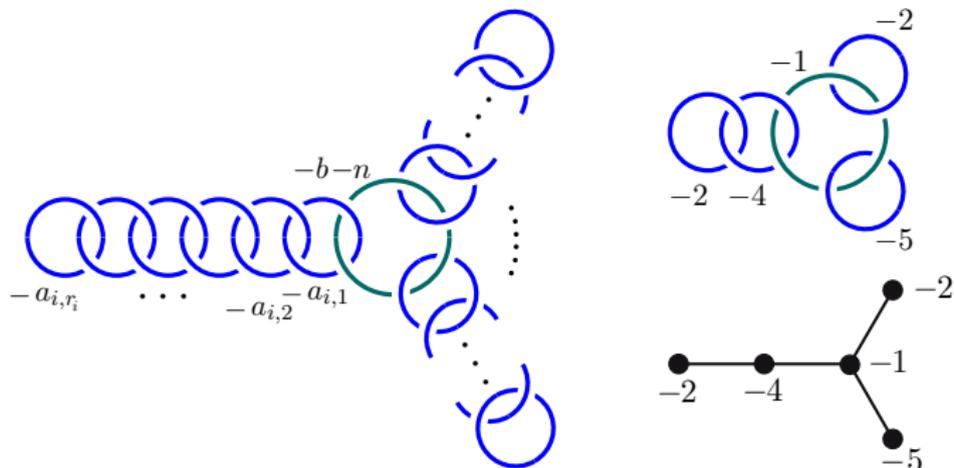
$$\begin{aligned}
 & (b; \dots, (\alpha_i, \beta_i), \dots) \\
 & \sim (b-1; \dots, (\alpha_i, \beta_i + \alpha_i), \dots) \\
 & \sim (b; \dots, (\alpha_i, \beta_i + \alpha_i), \dots, (\alpha_j, \beta_j - \alpha_j), \dots) \\
 \Rightarrow & b + \sum_{i=1}^n \frac{\beta_i}{\alpha_i} \text{ is invariant.}
 \end{aligned}$$



(3,1)

Seifert manifold : 3-manifolds that admit S^1 -action

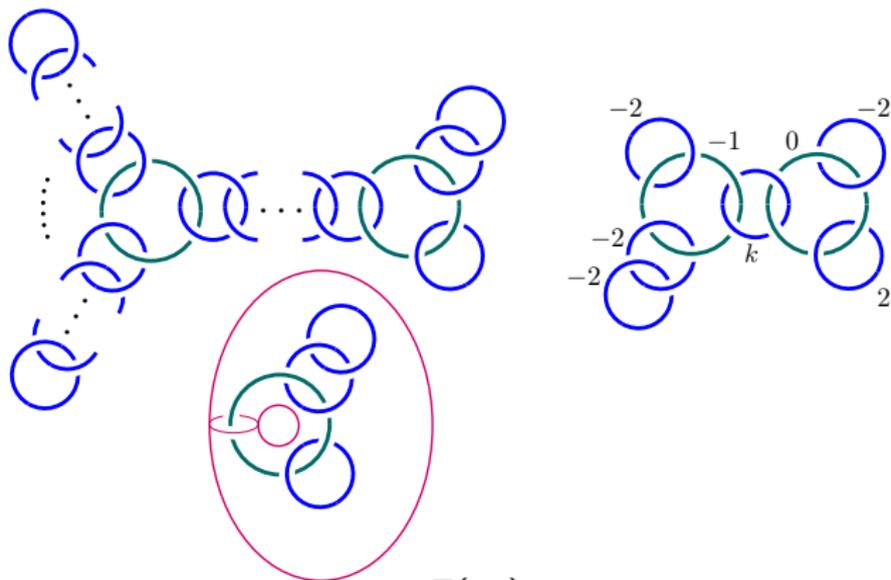
A diagram of $S(b; (\alpha_1, \beta_1), (\alpha_2, \beta_2), \dots, (\alpha_n, \beta_n))$



$$\frac{\alpha_i}{\alpha_i - \beta_i} = a_{i,1} - \frac{1}{a_{i,2} - \dots - \frac{1}{a_{i,n}}}$$

ex. $S(-2; (2, 1), (5, 4), (7, 5))$

Graph manifold : obtained from some Seifert pieces by pasting along boundary tori



Decomposing torus

$E(3_1)$

$Kb \tilde{\times} I$

ex. $D((2, 1), (3, 1)) \cup_{Mk} D((2, 1), (2, -1))$

Decomposition of 3-manifolds [W. Thurston]

Yi Liu's talk

By sphere- and torus- decomposition, any compact orientable 3-manifold can be decomposed into pieces :

(A) Hyperbolic	(B) Seifert
(1) Toroidal	(0) Reducible

Decomposition of 3-manifolds [W. Thurston]

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(1) Toroidal	(0) Reducible

Exceptional Dehn surgery

For a hyperbolic manifold M having a torus boundary, **Dehn filling** by a solid torus **can be non-hyperbolic !**

But, it is known that, for M , there exists **finite** such fillings. Thus, they are called **exceptional Dehn filling/ surgery**.

We may say “**Seifert surgery**”, “**Toroidal surgery**”, and so on. A solid torus filling is classified by the image of the meridian, called **slope** $\gamma \subset \partial M$. In the case M is a knot exterior, slopes are parametrized by $\overline{\mathbb{Q}} = \mathbb{Q} \cup \{\infty\}$.

Exceptional surgery along two bridge knots

[Brittenham-Wu '01]

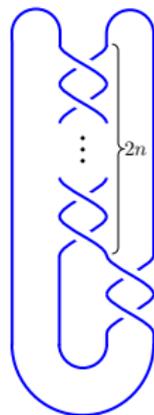
Seifert surgery happens only for (up to mirror image)

$$K_{[-2n,2]}$$

$n = -1$: Figure eight knot

$n = 1$: Right-handed trefoil

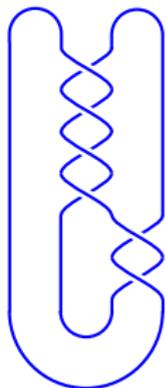
(except Torus knots $T(2, q)$)



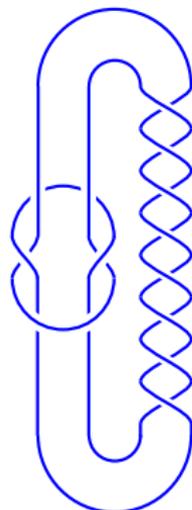
- Seifert : slope 1, 2, 3, Toroidal : slope 0, 4
- $n = -1$ is special. Seifert : $\pm 1, \pm 2, \pm 3$, Toroidal : 0, ± 4
- Toroidal : 0-surgery along $K_{[b,c]}$ with odd b and even c

Remark [Akbulut '91] “relative exotic pair”

$$M^3(K, -1) \cong M^3(K', -1) \quad \text{but} \quad X^4(K, -1) \not\cong X^4(K', -1)$$



$$K = K[-4, 2]$$

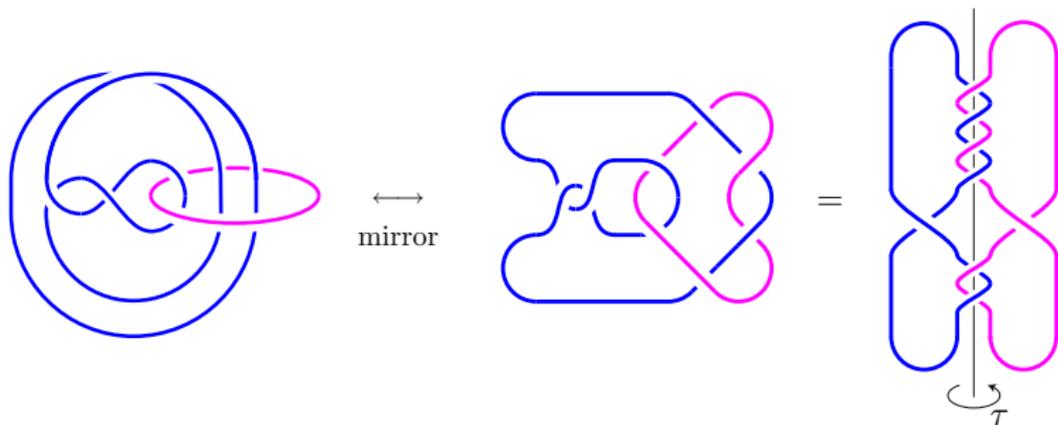


$$K' = P(-3, 3, -8)$$

This K is not slice (not 6_1 in Abe's talk).

The Mazur link

ML = the mirror image of the true* Mazur Link,
hyp. vol. = 4.749...

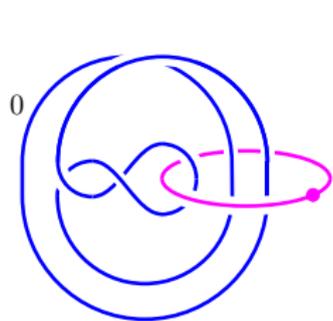


\exists involution τ Symmetry switching components

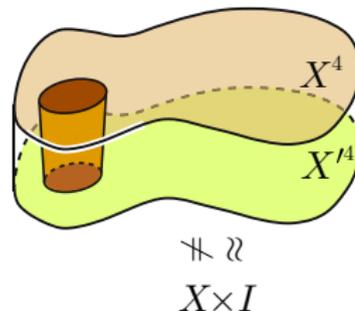
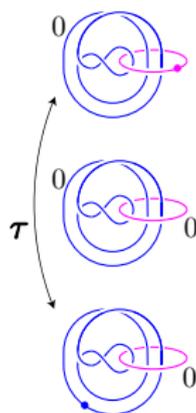
Not "false" Mazur link by [Prof. Y. Matsumoto]

The Mazur manifold⁴

is contractible but not B^4 . The boundary $(ML; 0, 0)$ is not S^3
 hyp. vol. = 2.259...



4-dim 0-, 1-, 2- handles

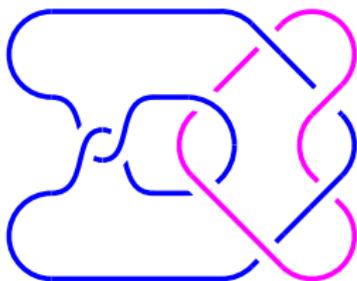


Akbulut **Cork** = “exoticity maker”

There exists an 4-dim exotic pair X and X' related to each other by cork twists τ .

Fact ([Y 2014 Nov.]

There exist some lens space (and $lens\#lens$) surgeries along ML.



$$(ML; 2, 6) = L(11, 3)$$

$$(ML; 2, 7) = L(13, 8)$$

$$(ML; 3, 4) = L(11, 2)$$

$$(ML; 3, 5) = L(2, 1)\#L(7, 2)$$

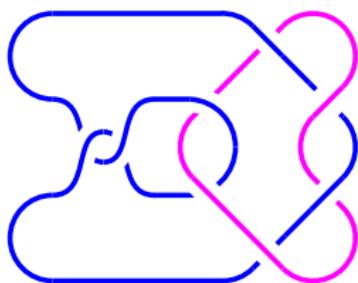
$$(ML; 3, 6) = L(17, 10)$$

$$(ML; 4, 4) = L(3, 2)\#L(5, 2)$$

$$(ML; 4, 5) = L(19, 8)$$

Fact ([Y 2014 Nov.]

There exist some lens space (and $\text{lens}\# \text{lens}$) surgeries along ML .



$$(ML; 2, 6) = L(11, 3)$$

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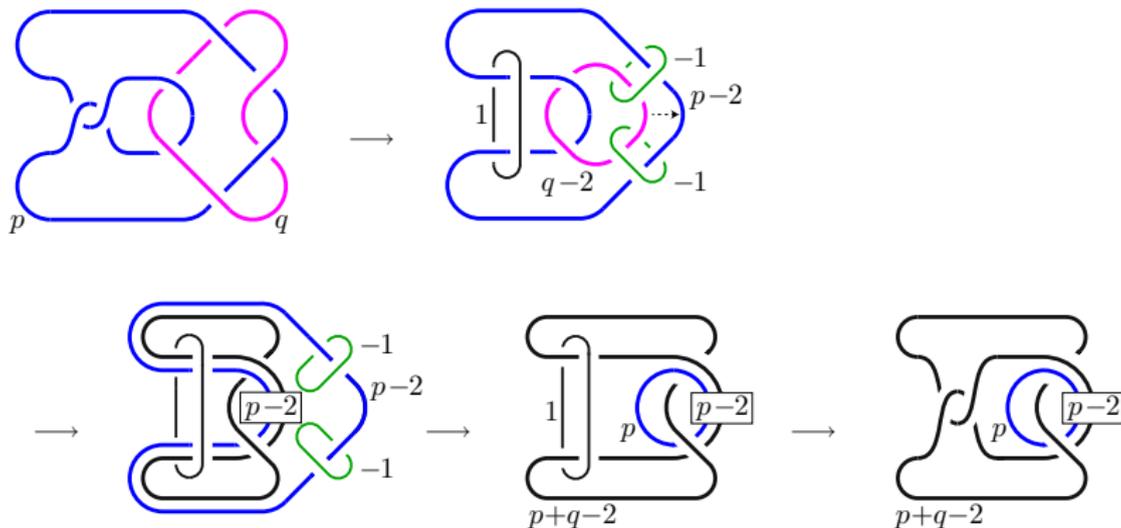
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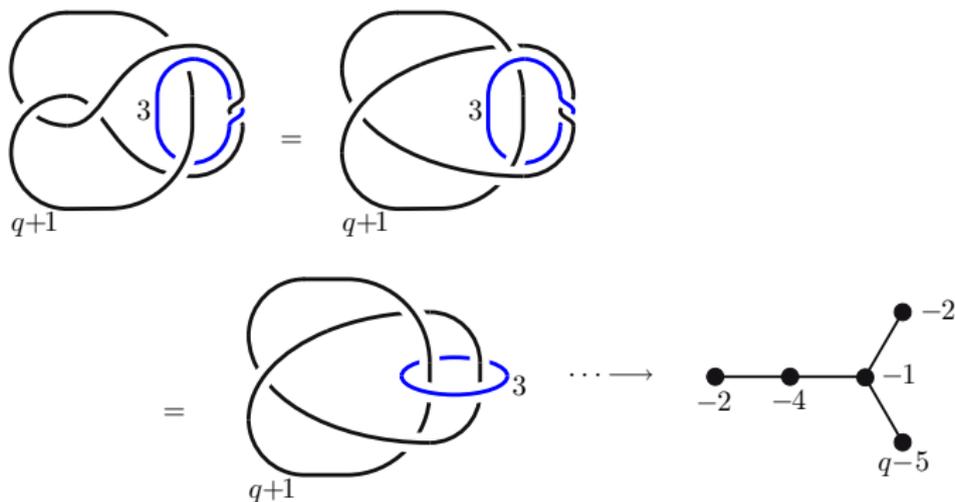
Table 1
 ML

	(2, 6)	(2, 7)
(3, 4)	(3, 5)	(3, 6)
	(4, 4)	(4, 5)

Proof of a lens space surgery $(ML; p, q)$



Case $p = 3$



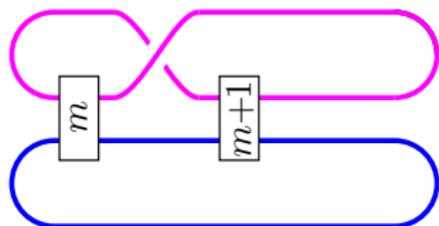
$$(ML; 3, 4) = L(11, 2)$$

$$(ML; 3, 5) = L(2, 1) \sharp L(7, 2)$$

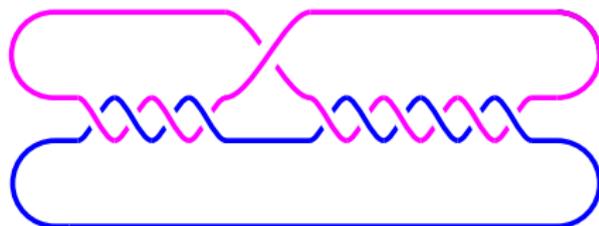
$$(ML; 3, 6) = L(17, 10)$$

The Mazur manifold is generalized to Akubult-Yasui Cork.

How about the Akubult-Yasui link AY_m , as a generalization of Mazur Link. It has an involution τ , too.



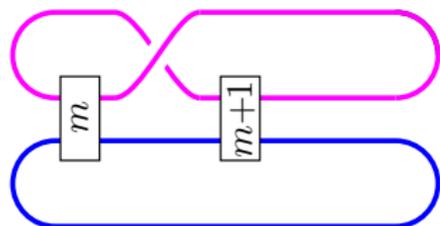
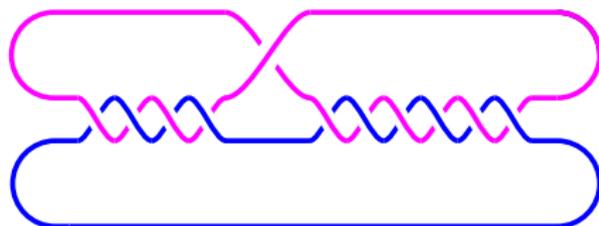
AY_m



ex. AY_2

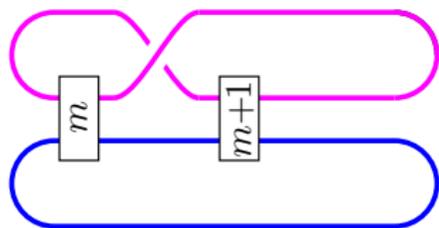
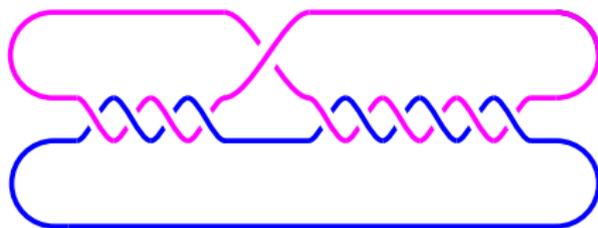
Two bridge link $K[2m, 1, 2(m+1)]$

Note that $AY_1 = ML$.

 AY_m ex. AY_2

Theorem ([Y])

There exist some lens space (and *lens#lens*) surgeries along AY_m .

 AY_m ex. AY_2

Theorem ([Y])

There exist some lens space (and *lens#lens*) surgeries along AY_m .

$$(AY_m; 2m, 2m + 4) = L(4m^2 + 8m - 1, 2m^2 + 3m - 2)$$

$$(AY_m; 2m + 1, 2m + 2) = -L(4m^2 + 6m + 1, 4m + 1)$$

$$(AY_m; 2m + 2, 2m + 3) = -L(4m^2 + 10m + 5, 4m + 3)$$

$$(AY_m; 2m + 1, 2m + 3) = L(2, 1)\# - L(2m^2 + 4m + 1, 2m + 1)$$

$$(AY_m; 2m + 2, 2m + 2) = -L(2m + 1, m)\# - L(2m + 3, 2)$$

Table 2 Same "pattern" for $m > 1$. Only $m = 1$ is special.

lens#lens, special cases

$$\downarrow p + q = 4m + 4$$

ML		$(2, 6)$	$(2, 7)$
	$(3, 4)$	$(3, 5)$	$(3, 6)$
		$(4, 4)$	$(4, 5)$
AY_2		$(4, 8)$	
	$(5, 6)$	$(5, 7)$	
		$(6, 6)$	$(6, 7)$

AY_m		$(2m, 2m + 4)$	
	$(2m + 1, 2m + 2)$	$(2m + 1, 2m + 3)$	
		$(2m + 2, 2m + 2)$	$(2m + 2, 2m + 3)$

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ML		(2, 6)	(2, 7)
	(3, 4)	(3, 5)	(3, 6)
		(4, 4)	(4, 5)

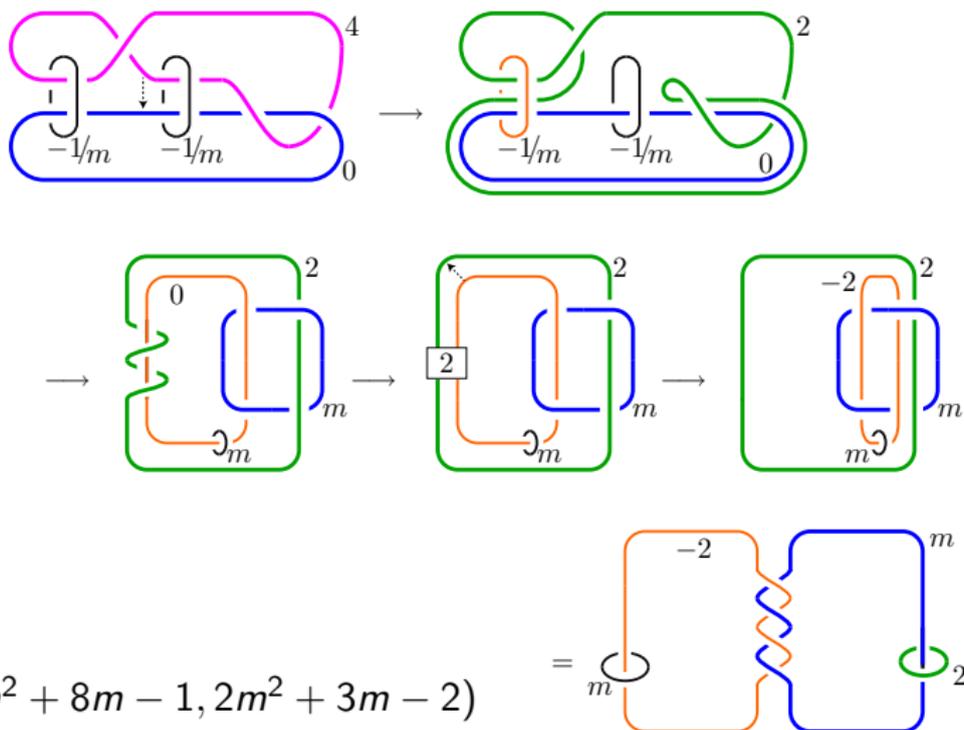
AY ₂		(4, 8)	
	(5, 6)	(5, 7)	
		(6, 6)	(6, 7)

AY _m		(2m, 2m + 4)	
	(2m + 1, 2m + 2)	(2m + 1, 2m + 3)	
		(2m + 2, 2m + 2)	(2m + 2, 2m + 3)

Conj. [Y, in March 2015]

This is the complete list of lens space surgeries on AY_m .

Proof of the lens space surgery $(AY_m; 2m, 2m + 4)$ for any m



□

Using MPR's results

Martelli-Petronio-Roukema's work :

Exceptional Dehn surgery

on the minimally twisted five-chain link,

Comm. Anal. Geom. **22** (2014) no. 4, 689–735.

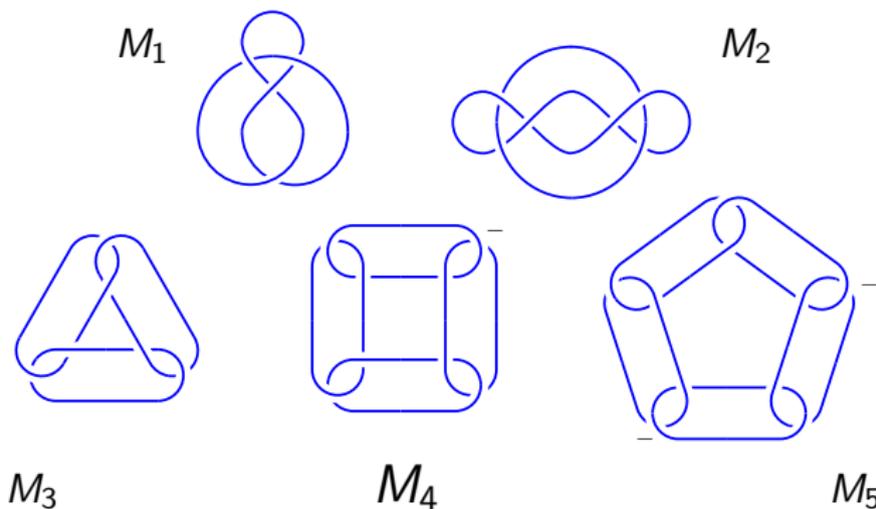
Thanks to Dr. Yuichi KABAYA

and Teragaito's talk on '09

Theorem ([Martelli-Petronio-Roukema '14])

*Using computer, Completely decide **all** exceptional Dehn surgeries along the minimally twisted five-chain link M_5 .*

The Minimally Twisted five-Chain link



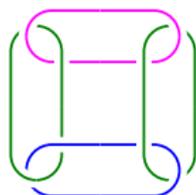
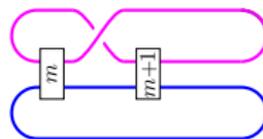
Remark. M_{n+1} is obtained from M_n by blow-up.

M_4 : 8_2^4 : Minimal volume among 4 cusp hyp. [Yoshida '13]

$M_3 = Pr(2, 2, 2)$, the magic link [Kin-Kojima-Takasawa '13]

M_2 : the Whitehead link, M_1 : the figure-eight knot 4_1 .

We can study $AY_m(p, q)$ by M_4


 M_4

 AY_m

$$AY_m = M_4 \left(-\frac{1}{m}, \emptyset, -\frac{1}{m+1}, \emptyset \right)$$

and thus

$$\begin{aligned} &AY_m(2m + a, 2m + b) \\ &= M_4 \left(-\frac{1}{m}, a - 1, -\frac{1}{m+1}, b - 1 \right) \end{aligned}$$

MPR's **SIX MOVES** on $(M_4; \alpha_1, \alpha_2, \alpha_3, \alpha_4)$ ($\alpha_i \in \overline{\mathbb{Q}} = \mathbb{Q} \cup \{\infty\}$)

Lem. [MPR] These moves do not change (up to mirror image) the manifold.

$$(1) \quad (\alpha_1, \alpha_2, \alpha_3, \alpha_4) \mapsto (\alpha_4, \alpha_1, \alpha_2, \alpha_3)$$

$$(2) \quad (\alpha_1, \alpha_2, \alpha_3, \alpha_4) \mapsto (\alpha_4, \alpha_3, \alpha_2, \alpha_1)$$

$$(3) \quad (\alpha_1, \alpha_2, \alpha_3, \alpha_4) \mapsto \left(\frac{\alpha_1 - 2}{\alpha_1 - 1}, \frac{\alpha_2 - 2}{\alpha_2 - 1}, \frac{\alpha_3 - 2}{\alpha_3 - 1}, \frac{\alpha_4 - 2}{\alpha_4 - 1} \right)$$

$$(4) \quad (\alpha_1, \alpha_2, \alpha_3, \alpha_4) \mapsto \left(2 - \alpha_1, \frac{\alpha_2}{\alpha_2 - 1}, 2 - \alpha_3, \frac{\alpha_4}{\alpha_4 - 1} \right)$$

$$(5) \quad (-1, \alpha_2, \alpha_3, \alpha_4) \mapsto (-1, \alpha_3 - 1, \alpha_2 + 1, \alpha_4)$$

$$(6) \quad (-1, -2, -2, \alpha) \mapsto (-1, -2, -2, -\alpha - 4)$$

Theorem ([Martelli-Petronio-Roukema '14])

“($M_4; \alpha_1, \alpha_2, \alpha_3, \alpha_4$) is *non-hyperbolic*”

$\Leftrightarrow (\alpha_1, \alpha_2, \alpha_3, \alpha_4)$ is in the list below, *up to six moves (1)...(6)*

No.	coef.	Manifolds
(O)	($0, a/b, c/d, e/f$)	$D((b, b-a), (f, f-e))$ $\cup_H D((2, 1), (c-2d, d))$
(A)	($\infty, a/b, c/d, e/f$)	$S((a, b), (d, -c), (e, f))$
(B)	($-1, -2, -1, a/b$)	$A((b, -a))/_H$
(d2)	($-1, -2, -3, -4$)	$D((2, 1), (3, 1)) \cup_{M_2} D((2, 1), (2, -1))$
(d3)	($-1, -3, -2, -3$)	$D((2, 1), (3, 1)) \cup_{M_3} D((2, 1), (2, -1))$
(d4)	($-2, -2, -2, -2$)	$D((2, 1), (3, 1)) \cup_{M_4} D((2, 1), (2, -1))$

Pasting matrices : $H = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, $M_k = \begin{pmatrix} -1 & k \\ 1 & -(k-1) \end{pmatrix}$, by using a base system {Section, Fiber} of the boundary torus. |(1, 2)-entry| is geometrically well-defined : Intersection number of the fibers.

Contemporal !

According to Masai's talk in May '15,

The MPR used the computer program **SnapPea**, thus their proof on hyperbolicity may be not enough, strictly. But, this problem is solved by

Verified computations for hyperbolic 3-manifolds, Exp. Math.

N. Hoffman, K. Ichihara, M. Kashiwagi,
H. Masai, S. Oishi, and A. Takayasu

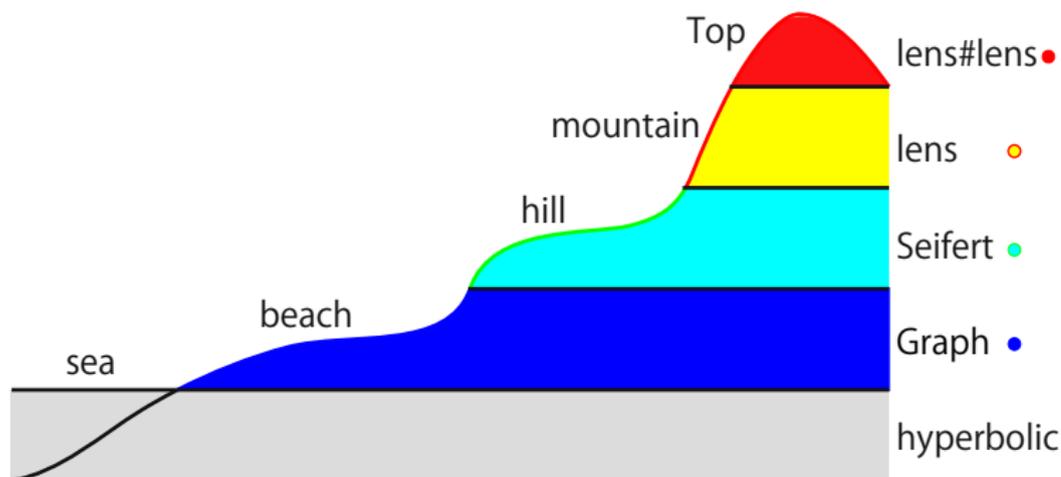
Computer program **HIKMOT** supported by computer science.

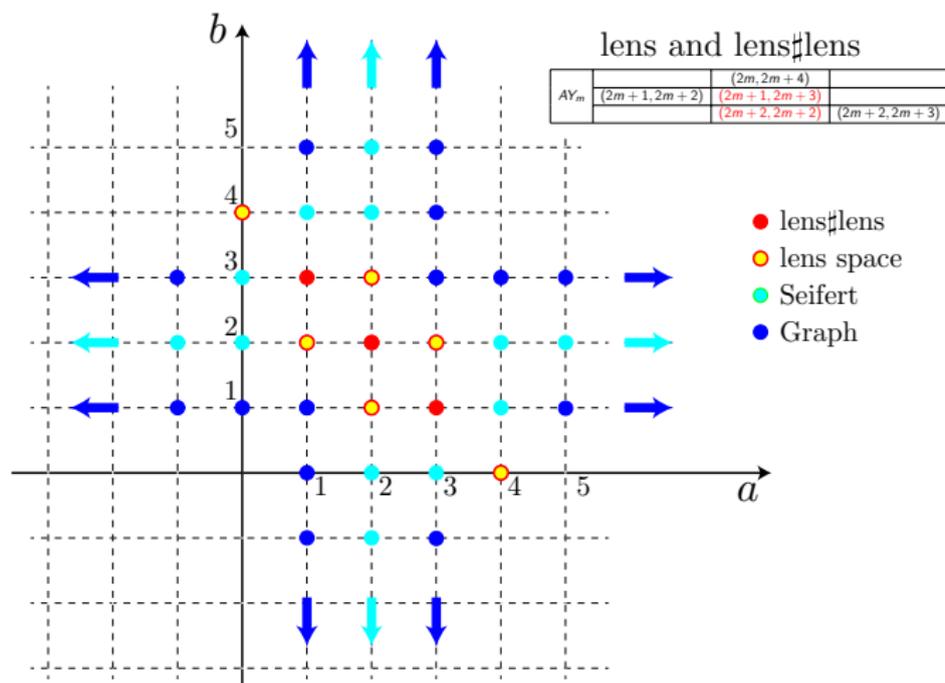
If **HIKMOT** says "it is hyperbolic", then it is hyperbolic.

The existence of a solution of hyperbolic structure eq. is verified.

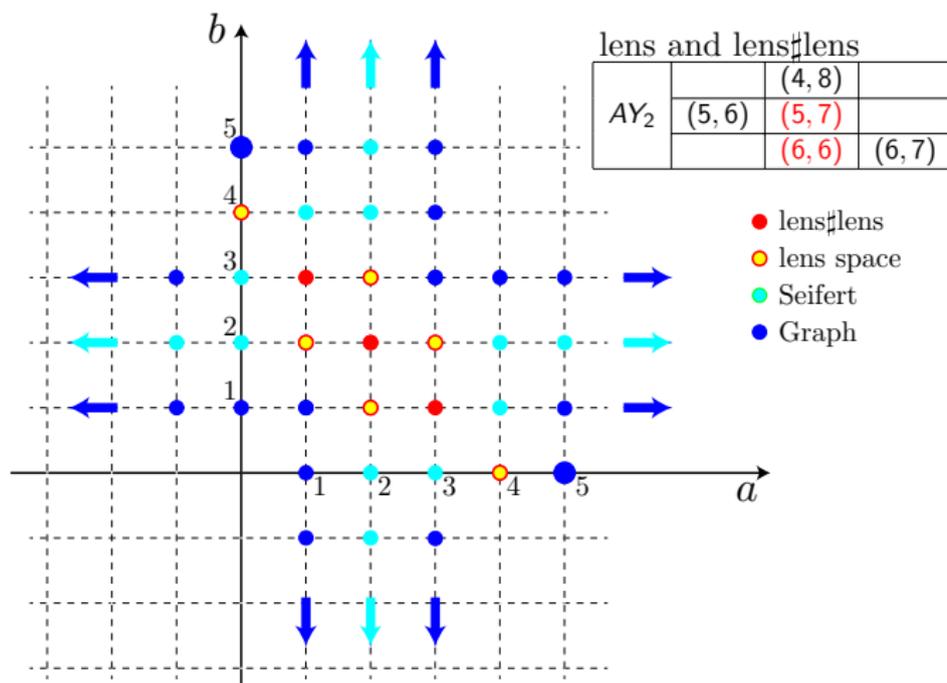
Main Results

Geography of Dehn surgeries along AY_m

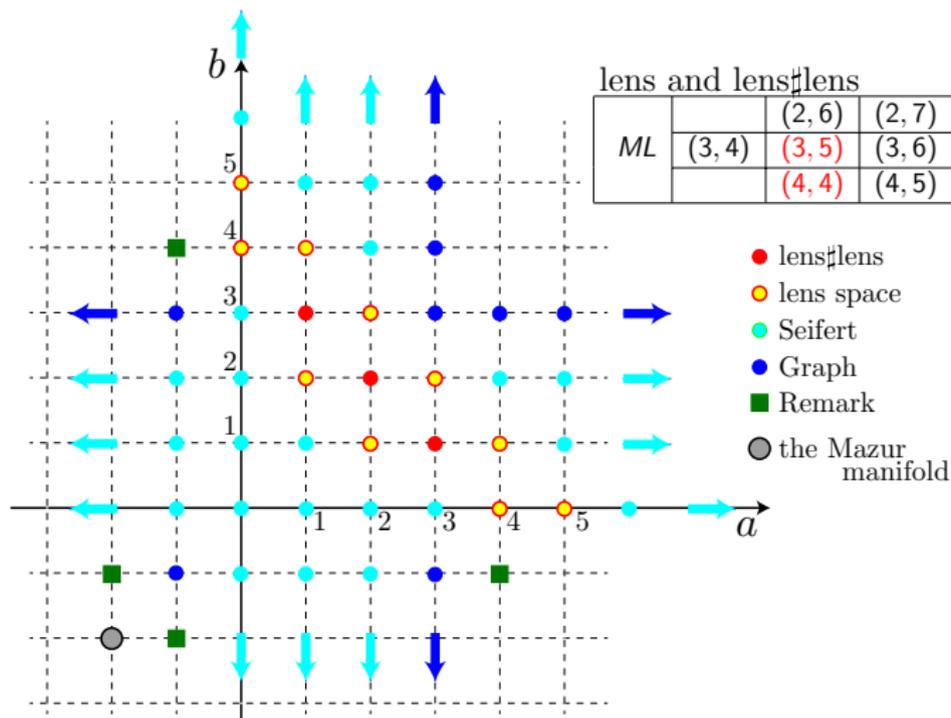




Dehn surgery $AY_m(2m+a, 2m+b)$ in general, ie $m \geq 3$.



Dehn surgery $AY_m(2m + a, 2m + b)$ with $m = 2$.

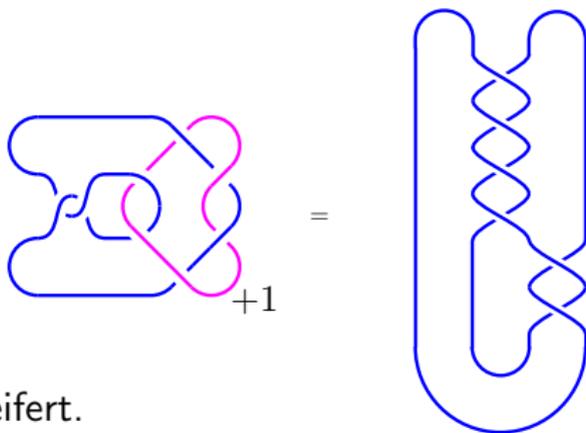


Dehn surgery $ML(2 + a, 2 + b)$ as $AY_m(2m + a, 2m + b)$ with $m = 1$

Remark The hardest case: $a = -1$

The knot $ML(+1, \emptyset) = K_{[-4,2]}$ and
 $ML(+1, 2+b) = (K_{[-4,2]}, 1+b)$.

Thus we can use Brittenham-Wu's results on two bridge knots.



$b = 0, 1, 2 \Rightarrow$ Seifert.

$b = -1, 3 \Rightarrow$ Troidal.

$b = -1 : (K_{[-4,2]}, 0) = ML(1, 1) = M_4(-1, -2, -1/2, -2)$
 $= M_4(-1, -3/2, -1, -2) = A((2, 3))/H$

$b = -2 : (K_{[-4,2]}, -1)$ (relative exotic pair to $(P(-3, 3, 8); -1)$)

[Again]

SIX MOVES on $(M_4; \alpha_1, \alpha_2, \alpha_3, \alpha_4)$ $(\alpha_i \in \overline{\mathbb{Q}} = \mathbb{Q} \cup \{\infty\})$

Lem. [MPR] These moves do not change (up to mirror image) the manifold.

$$(1) \quad (\alpha_1, \alpha_2, \alpha_3, \alpha_4) \mapsto (\alpha_4, \alpha_1, \alpha_2, \alpha_3)$$

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$$(5) \quad (-1, \alpha_2, \alpha_3, \alpha_4) \mapsto (-1, \alpha_3 - 1, \alpha_2 + 1, \alpha_4)$$

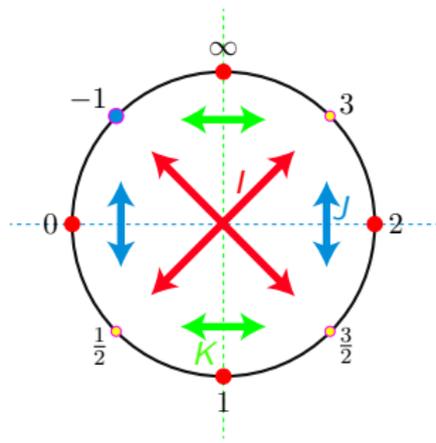
$$(6) \quad (-1, -2, -2, \alpha) \mapsto (-1, -2, -2, -\alpha - 4)$$

Moves (3), (4)

$$I(x) = \frac{x-2}{x-1}, \quad J(x) = \frac{x}{x-1}, \quad K(x) = 2-x,$$

$$I, J, K : \overline{\mathbb{Q}} \rightarrow \overline{\mathbb{Q}}$$

are involutions and satisfies a relation:



$$I^2 = J^2 = K^2 = IJK = 1$$

Move (5)

$$(-1, \alpha_2, \alpha_3, \alpha_4) \mapsto (-1, \alpha_3 - 1, \alpha_2 + 1, \alpha_4)$$

is also an involution. We only have to care

$$\begin{array}{cccc} (-1, & \alpha_2, & \alpha_3, & \alpha_4) \\ (-1, & \alpha_3 - 1, & \alpha_2 + 1, & \alpha_4) \\ (-1, & \alpha_2, & \alpha_4 + 1, & \alpha_3 - 1) \end{array}$$

and their orbits by dihedral moves (1), (2).

TAKE CARE :

the case **new** -1 **occurs** by Moves (3), (4) (ie, I, J, K).

Method : Once ignore $m = 1$ (The Mazur link), the special case.

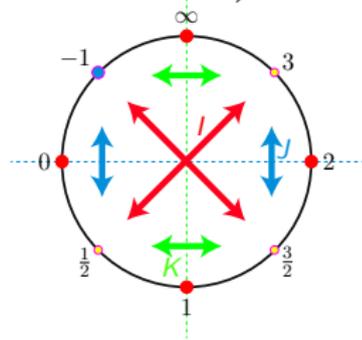
$$AY_m(2m + a, 2m + b) = M_4 \left(-\frac{1}{m}, a - 1, -\frac{1}{m+1}, b - 1 \right)$$

($a = 0$) By Move (5),

$$= M_4 \left(-1, -\frac{1}{m}, b - 1, -\frac{1}{m+1} \right)$$

$$= M_4 \left(-1, b - 2, \frac{m-1}{m}, -\frac{1}{m+1} \right)$$

$$= M_4 \left(-1, -\frac{1}{m}, \frac{m}{m+1}, b - 2 \right)$$



$\Rightarrow m > 2$ and $\{b - 1, b - 2\} \not\subset \{-1, 0, \frac{1}{2}, 1, \frac{3}{2}, 2, 3, \infty\}$ is hyp.
 $m = 2$ or $b = 0, 1, 2, 3, 4, 5$

Harder case ($a = 0, b = 5$) By Move (4),

$$= M_4 \left(-1, 3, \frac{m-1}{m}, -\frac{1}{m+1} \right) = M_4 \left(\frac{1}{2}, -1, 1 - m, \frac{2m+3}{m+1} \right) \dots$$

If $m = 2$, then ... , else then ...

Thank you very much!