

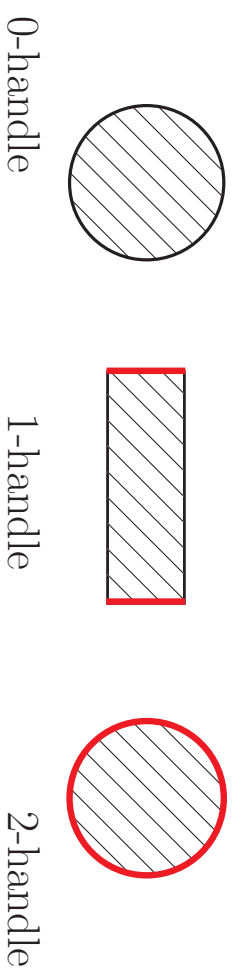
Kirby Calc. 入門

山田 裕一 (電気通信大学)

- [K] R. Kirby, “The topology of 4-manifolds”, Springer Lecture Notes **1374** (1989).
- [GS] R. Gompf & A. Stipsicz, “4-Manifolds and Kirby Calculus”, (1999).

§1. Handle Decomposition

- 2-dim.



- 3-dim.

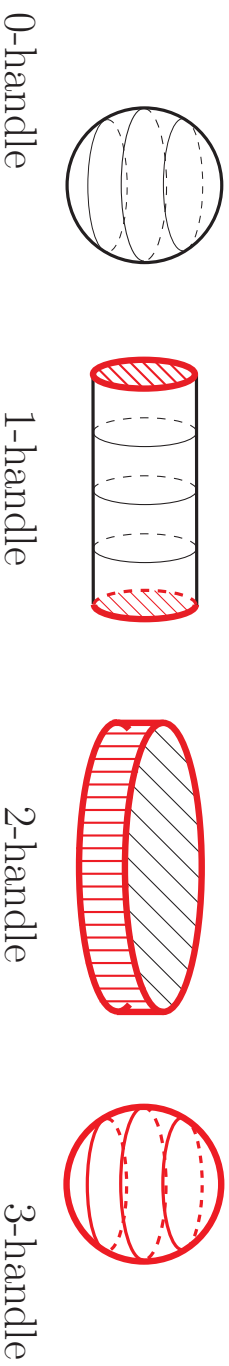
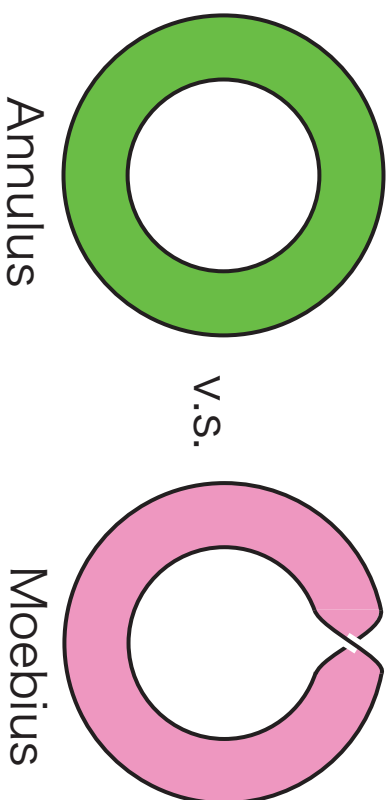
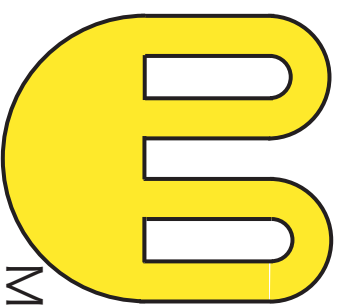


Figure 1-1 : 2-, 3-dim. handles

Why (and When) handles are useful?



v.s.



v.s.

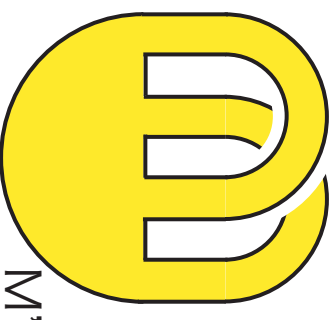
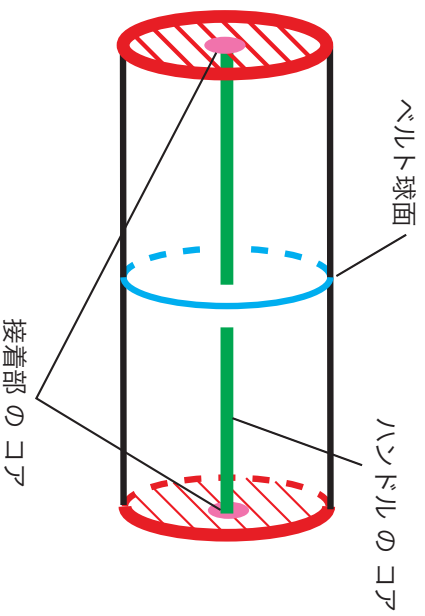


Figure 1-2 : homotopy eq. but not-homeo.

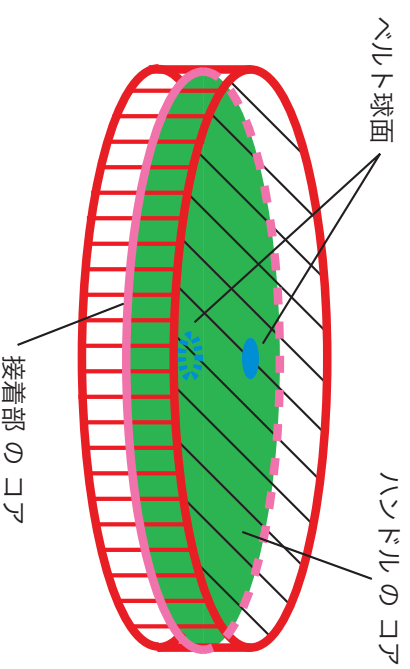
$(M \simeq M'$ but $M \not\cong M'$, $M \times [0, 1] \cong M' \times [0, 1])$

Terminology of handle

n -dim. i -handle	$D^i \times D^{n-i}$	handle Core	$D^i \times \{o\}$
Attaching part	$\partial D^i \times D^{n-i}$		
Boundary part		$D^i \times \partial D^{n-i}$	
Attach Core	$\partial D^i \times \{o\}$	its parallel	$\partial D^i \times \{p\}$
Belt sphere			$\{o\} \times \partial D^{n-i}$



1-handle



2-handle

Figure 1-3 : 3-dim. handles

1-handle is identifying the two balls

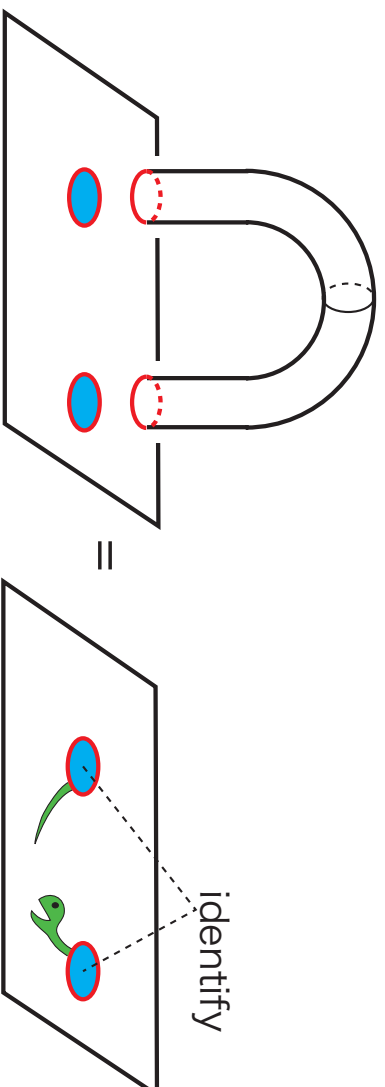
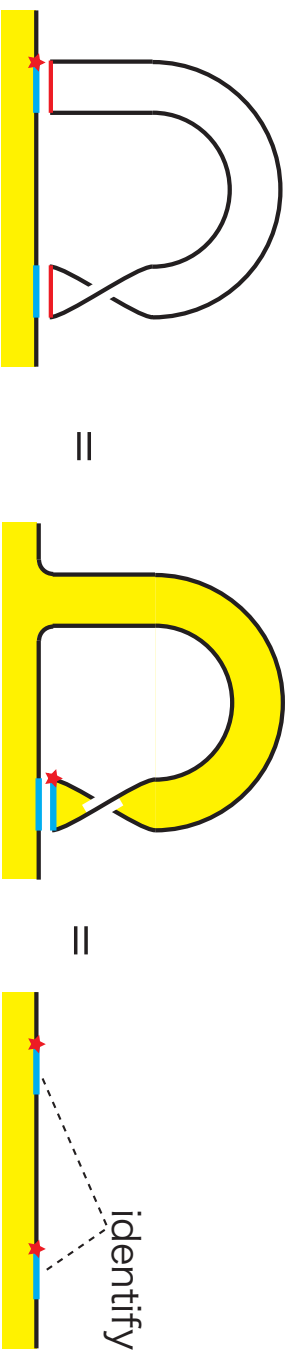


Figure 1-4 : 1-Handle

Only 1-handle can connect disjoint parts ...

Handle Slide (h_i^i slides over h_j^j)

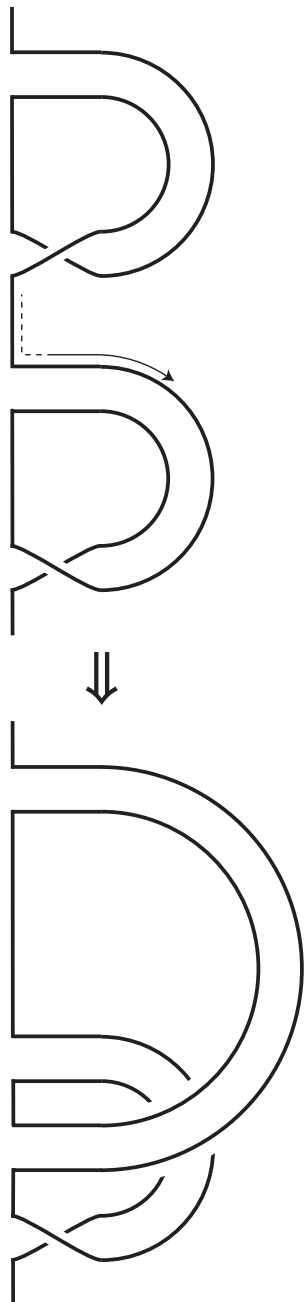


Figure 1-5 : Handle Slides

$$Mob \natural Mob \cong \text{punc}Kb, \quad \mathbf{RP}^2 \natural \mathbf{RP}^2 \cong Kb \text{ (i.e. } S^1 \times \tilde{S}^1)$$

Handle Cancel (h^i and h^{i+1} cancel, if “Belt(h^i) \cap At.core(h^{i+1}) = {1pt}”)

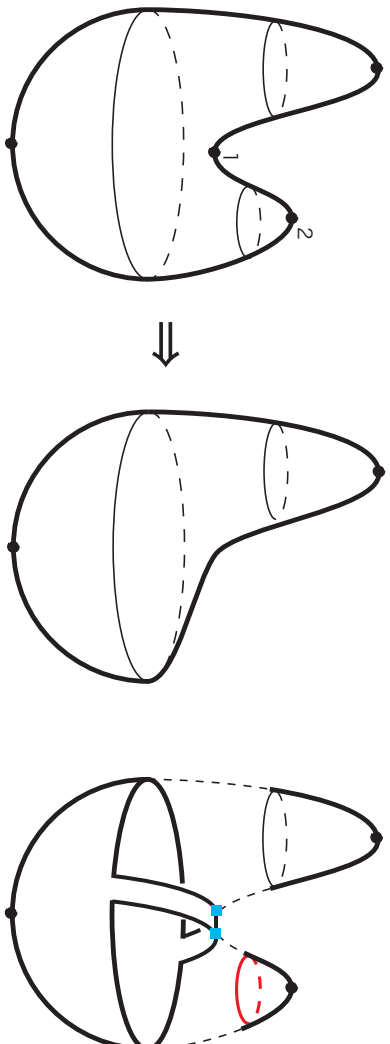


Figure 1-6 : Handle Cancel

i-handle presents *i*-chain, *i*-cycle, or *i*-homology

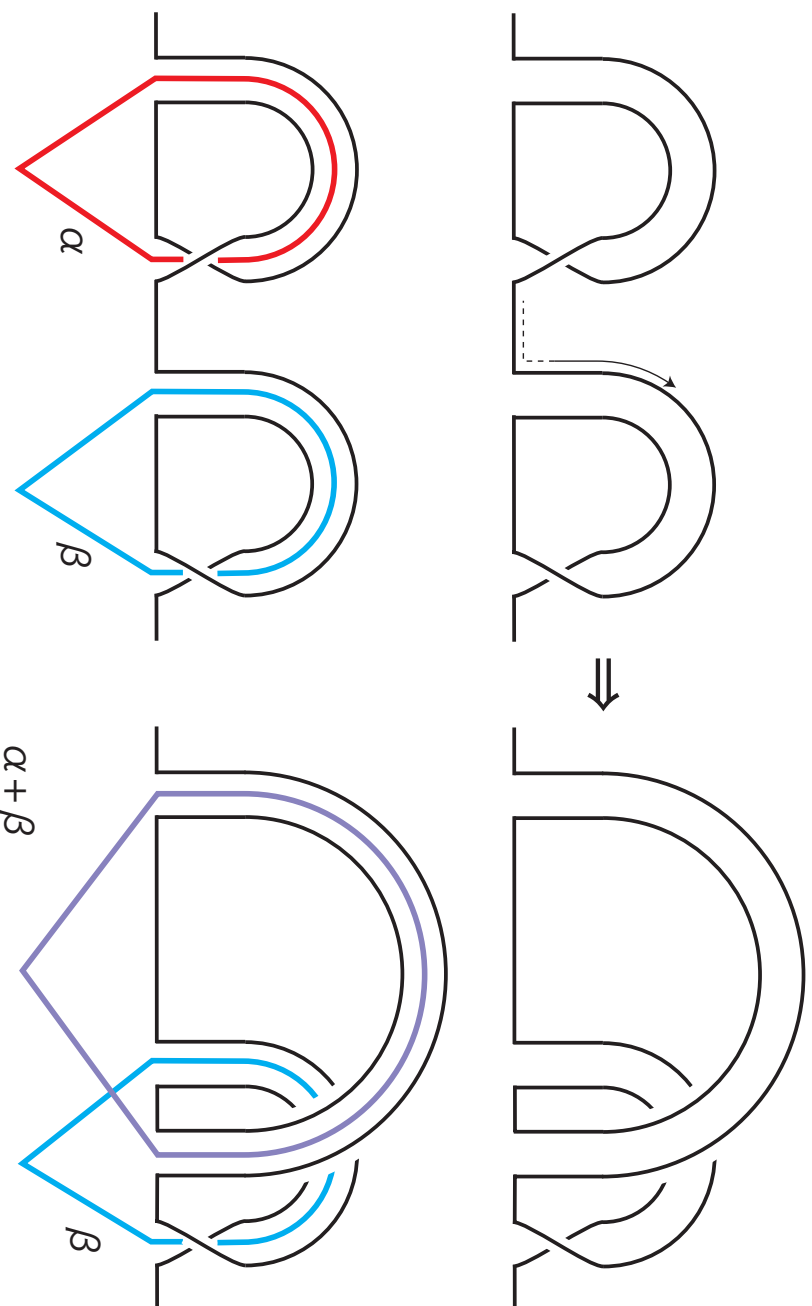


Figure 1-7 : Handle presents Homology

Handle slide is “+/- in homology”

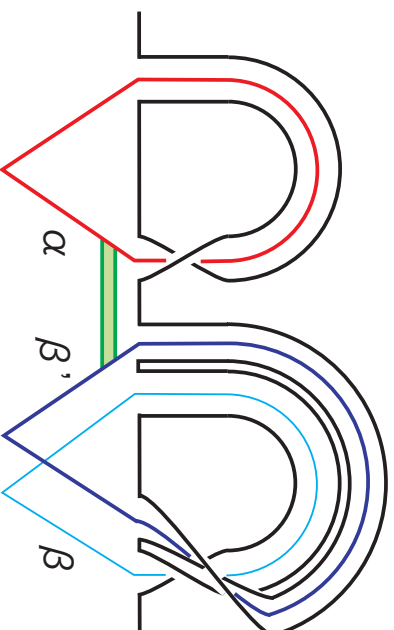
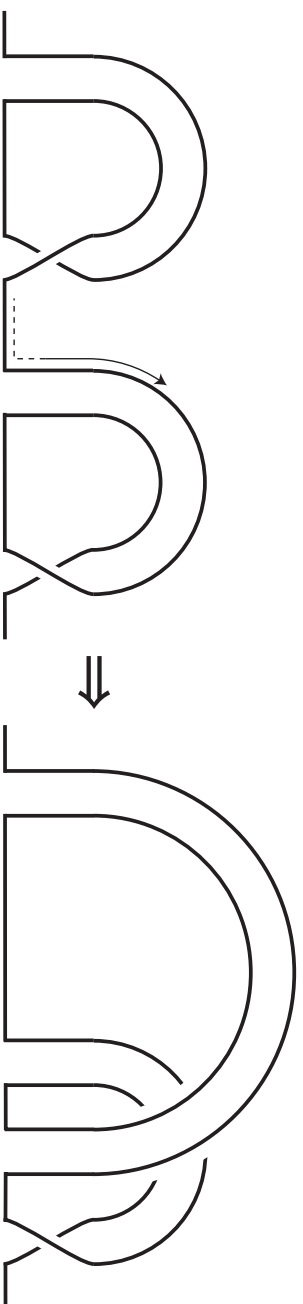
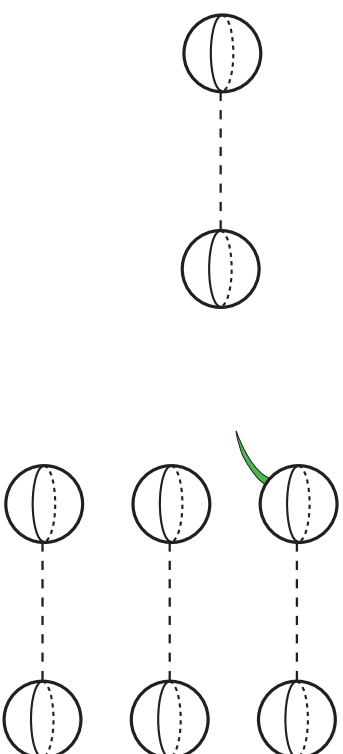


Figure 1-7'

§2. 4-dim. case

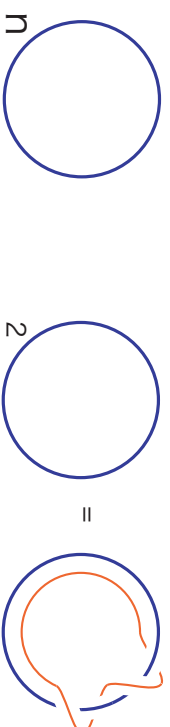
ex1.



$$S^1 \times D^3$$

$$\#_3(S^1 \times D^3) \text{ (or } \#_3(S^1 \times S^3))$$

ex2.



$$S^2 \times_n D^2 := \Gamma S^2 \text{ EOD } D^2 \text{ 束 with } Z \cdot Z = n \mathbf{1} \quad Z = \text{zero section}$$

$$\partial(S^2 \times_n D^2) \cong -L(n, 1).$$

ex3.

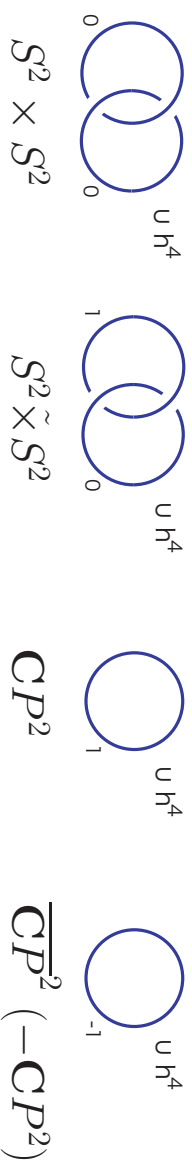


Figure 2-1 :

Blow-Up

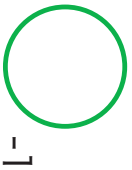
$$\mathbf{C}^2 \times \mathbf{C}P^1 \supset U := \{((z, w), [s : t]) \mid zt = ws\}$$

$$\begin{array}{ccc} & \downarrow pr.1 & \\ \mathbf{C}^2 & & \downarrow \pi := pr.1|_U \\ & & (z, w) \end{array}$$

Note

- (1) $\pi^{-1}(z, w) = ((z, w), [z : w])$ for $(z, w) \neq (0, 0)$
- (2) $\pi^{-1}(0, 0) \cong \mathbf{C}P^1 = S^2$ ($U \cong \text{punc}\mathbf{C}P^2$)

local coordinates of U

$$\begin{array}{ccccc} \mathbf{C} \times \mathbf{C} & \rightarrow & U & \leftarrow & \mathbf{C} \times \mathbf{C} \\ (z, t) & \rightarrow & ((z, zt), [1 : t]) & & \\ & & ((ws, w), [s : 1]) & \leftarrow & (w, s) \\ (z, t) & \rightarrow & & & (zt, \frac{1}{t}) \end{array}$$


In \mathbf{C}^2 , $(z, w) = (z, zt) = (ws, w)$.

2-handle slides Slide h_2 over h_1

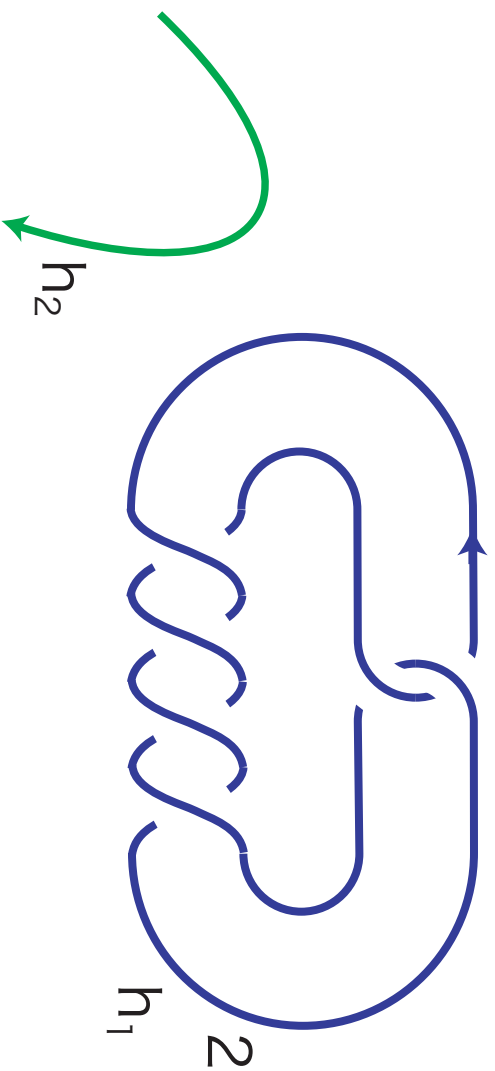


Figure 2-2 :

2-handle slides

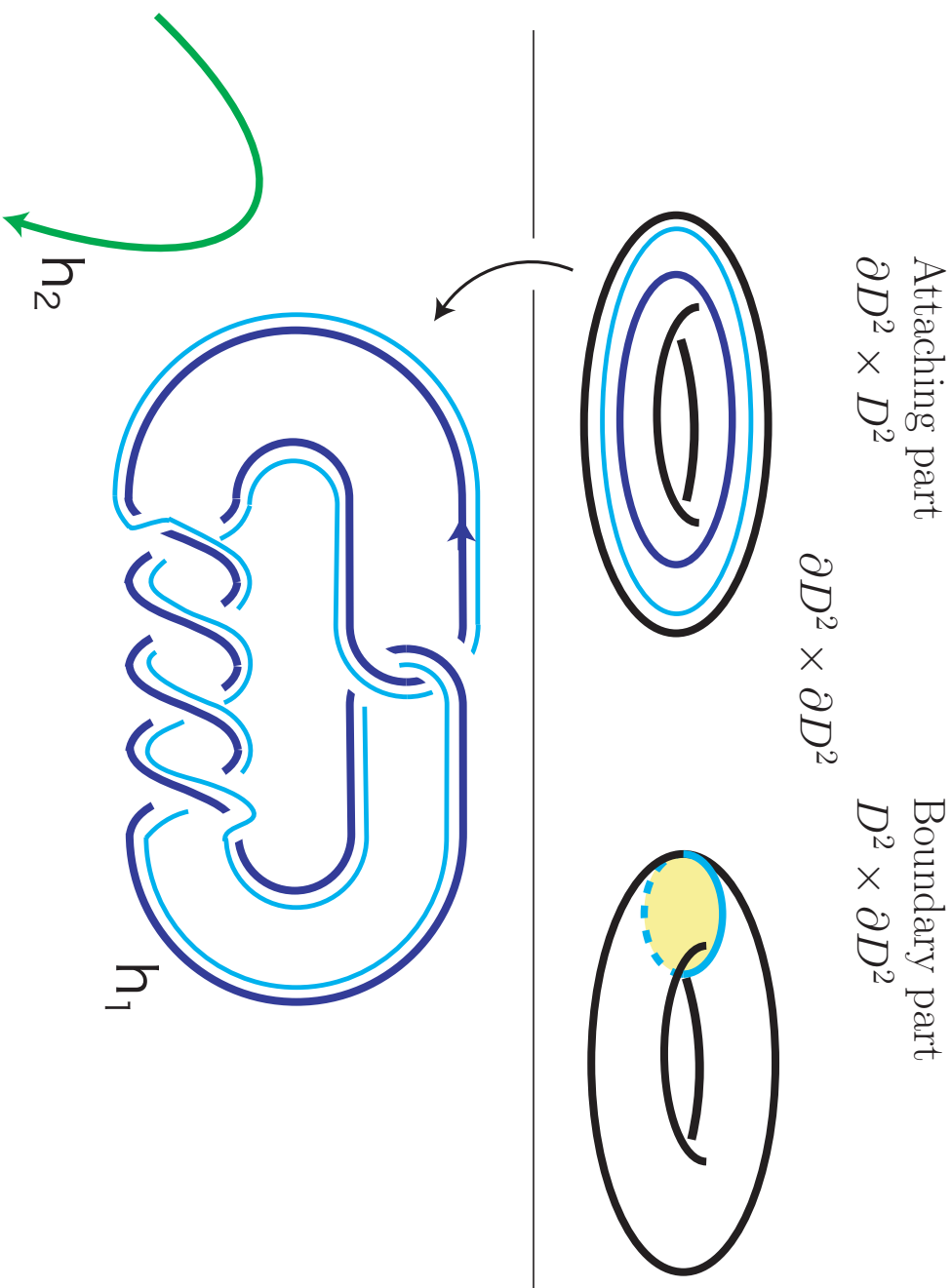


Figure 2-2(2) :

2-handle slides

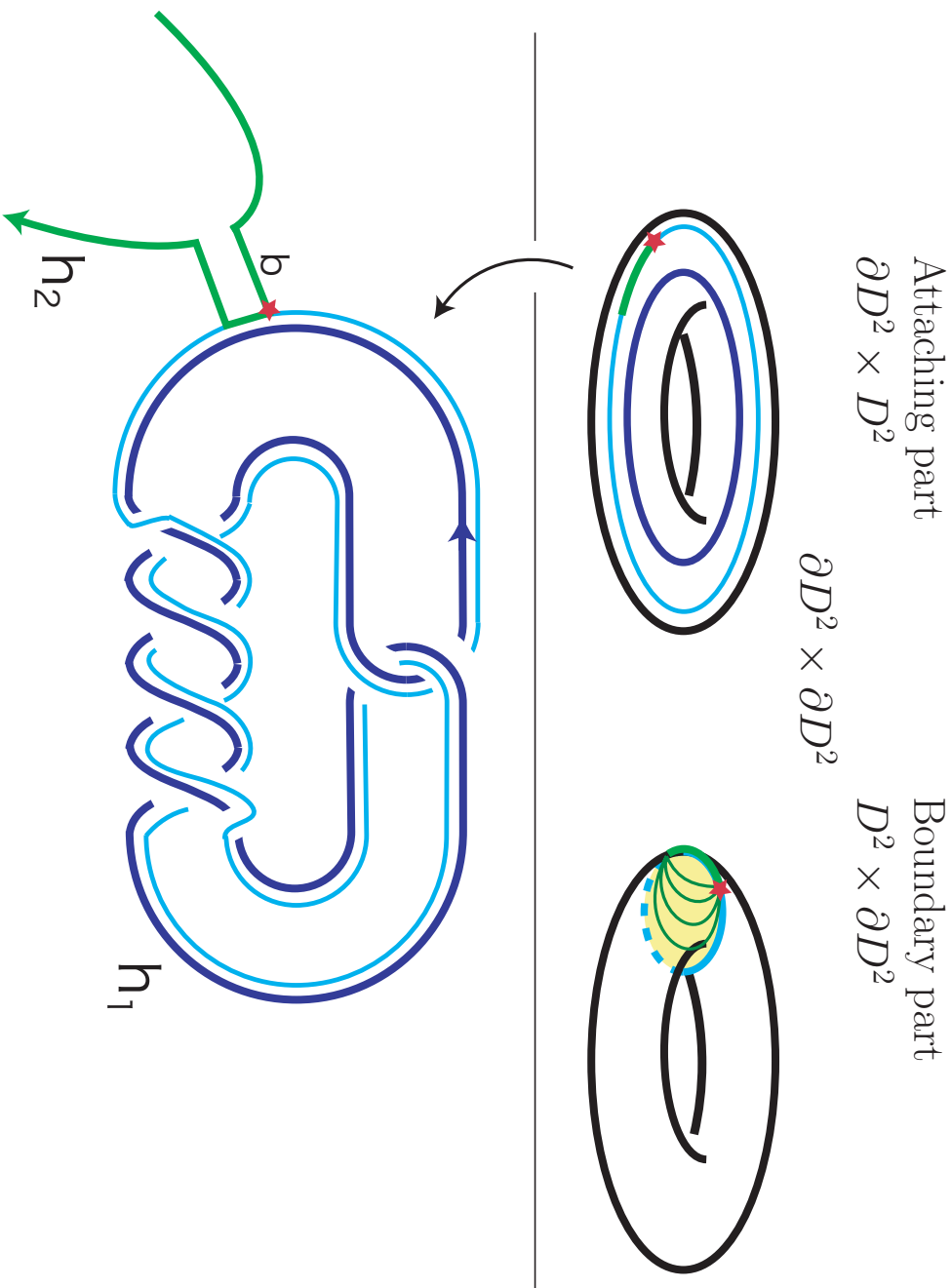


Figure 2-2(3) :

2-handle slides

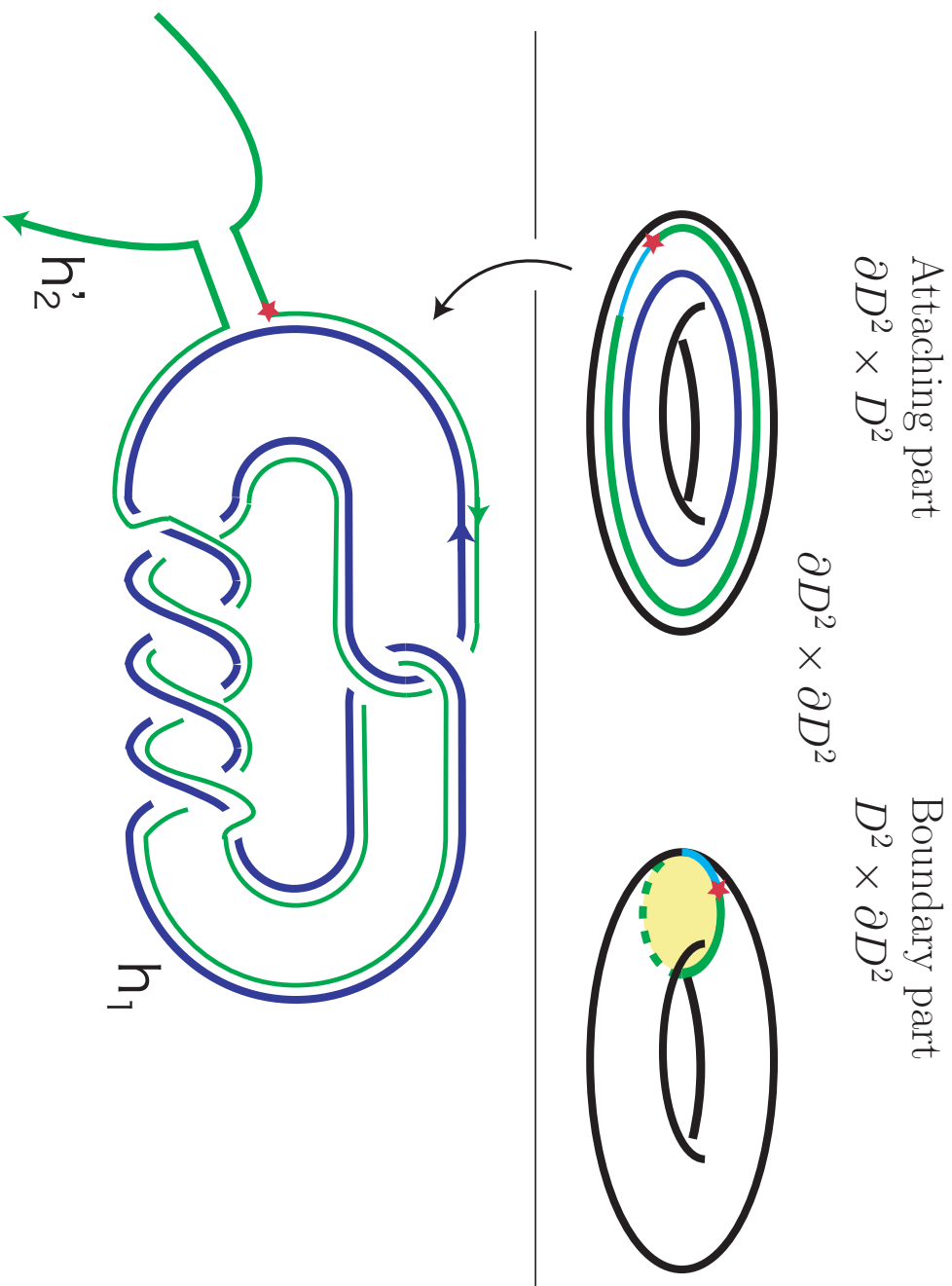


Figure 2-2(results) :

Framing of h_2' is

Useful Formula F0: “A component with 0-framed meridian” can be taken out.

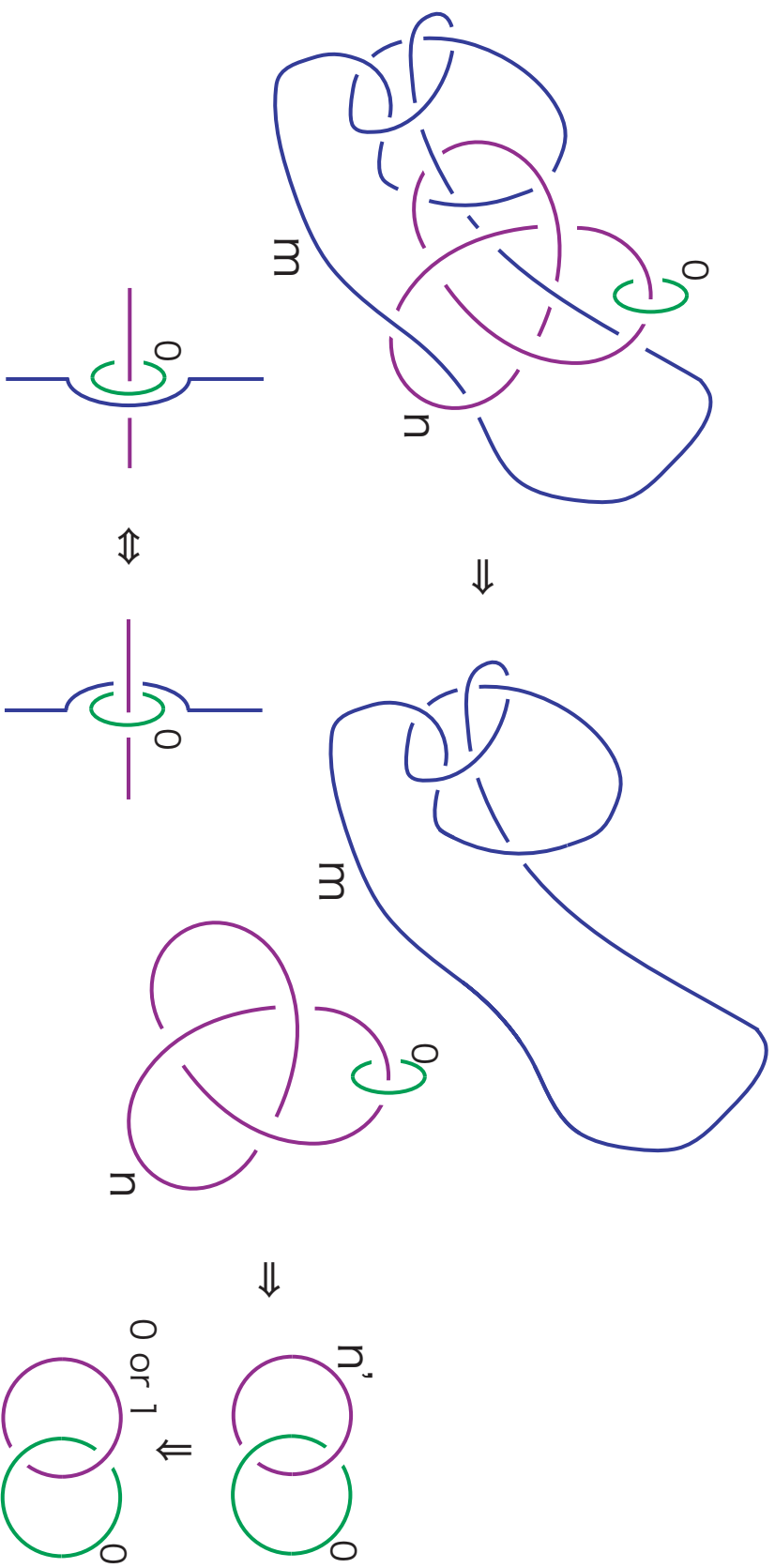
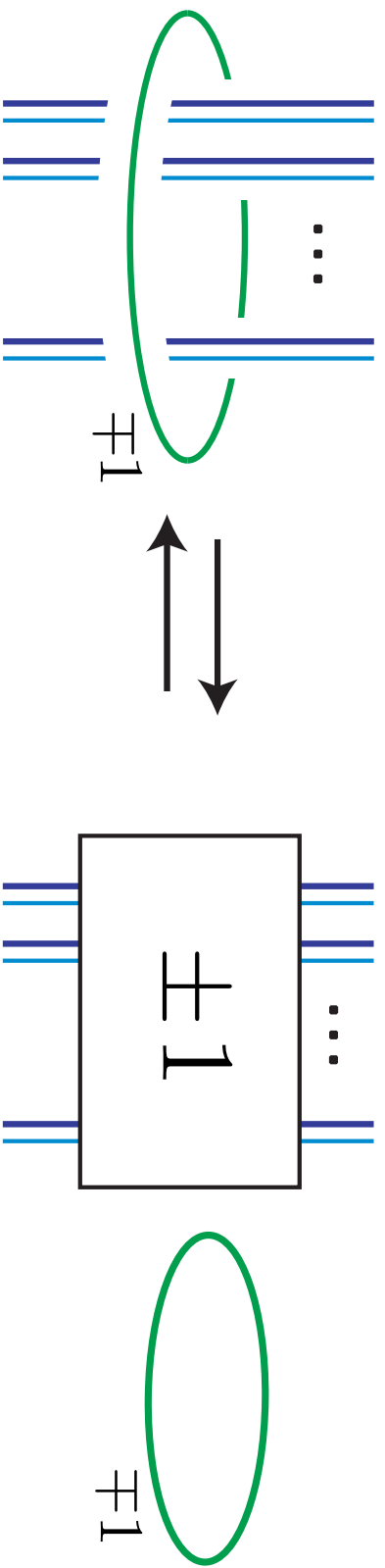


Figure 2-3 :

Useful Formula F1: related to Blow-up



Exercise

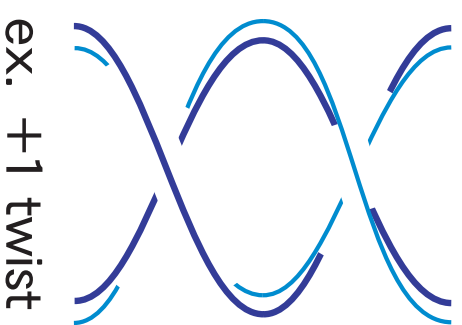
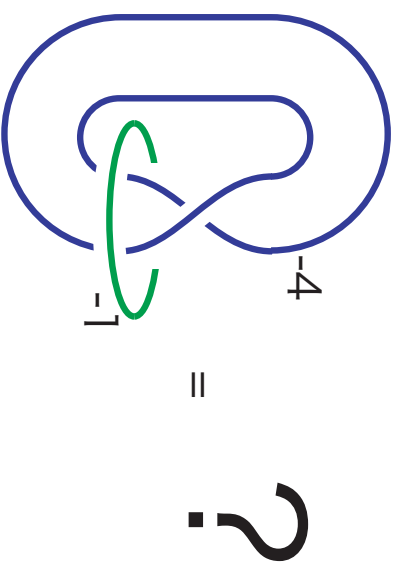
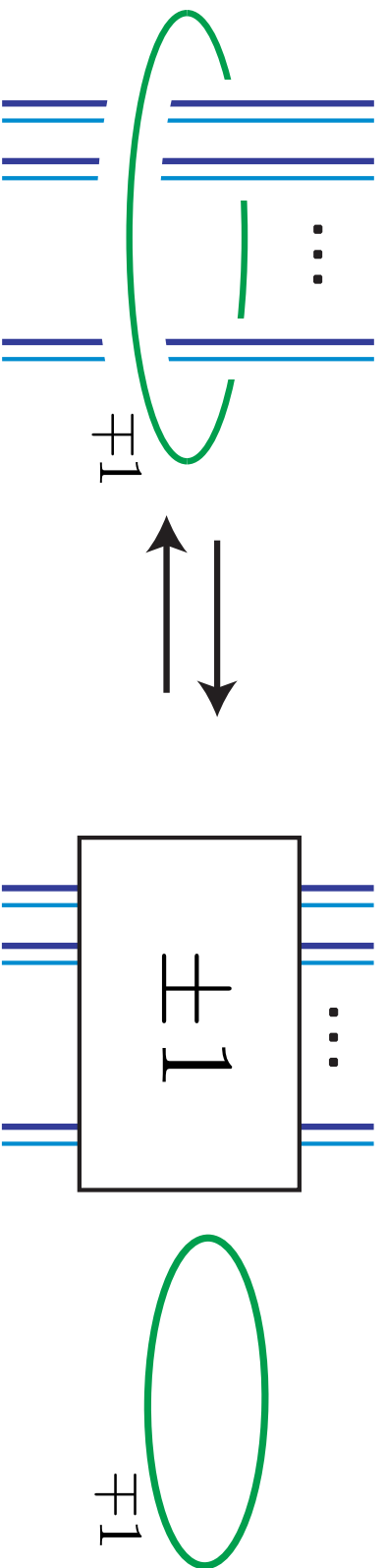


Figure 2-4 :

Useful Formula F1: related to Blow-up



Answer

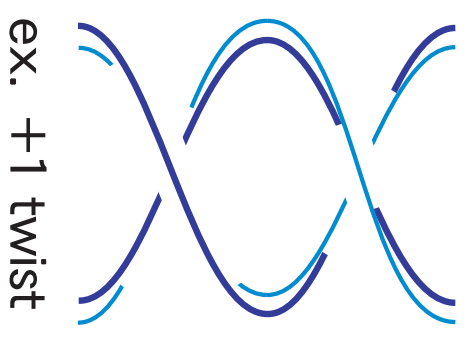
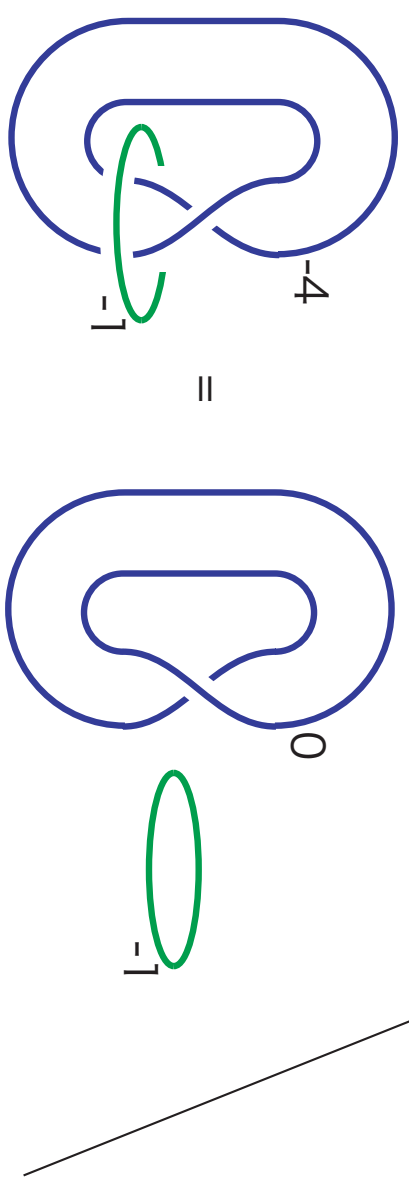


Figure 2-4a :

Intersection form = linking matrix.

$$E_8 = \begin{bmatrix} -2 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & -2 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & -2 \end{bmatrix}$$

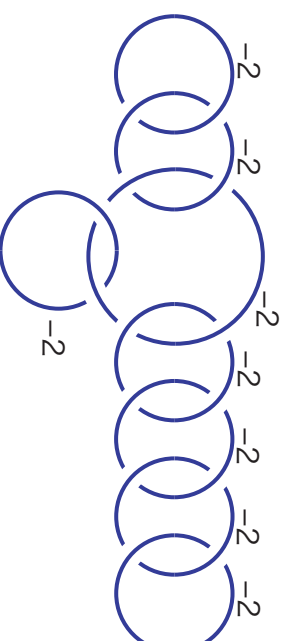


Figure 2-5 : Matrix E_8 and E_8 -manifold

$\partial E_8 = \Sigma(2, 3, 5) := \{ (x, y, z) \in S^5_\epsilon \subset \mathbf{C}^3 \mid x^2 + y^3 + z^5 = 0 \}$ “Poincare sphere”

Exercise. $(S^2 \times S^2) \# \overline{\mathbf{C}P^2} \cong \mathbf{C}P^2 \# \overline{\mathbf{C}P^2} \# \overline{\mathbf{C}P^2} \cong (S^2 \tilde{\times} S^2) \# \overline{\mathbf{C}P^2}$

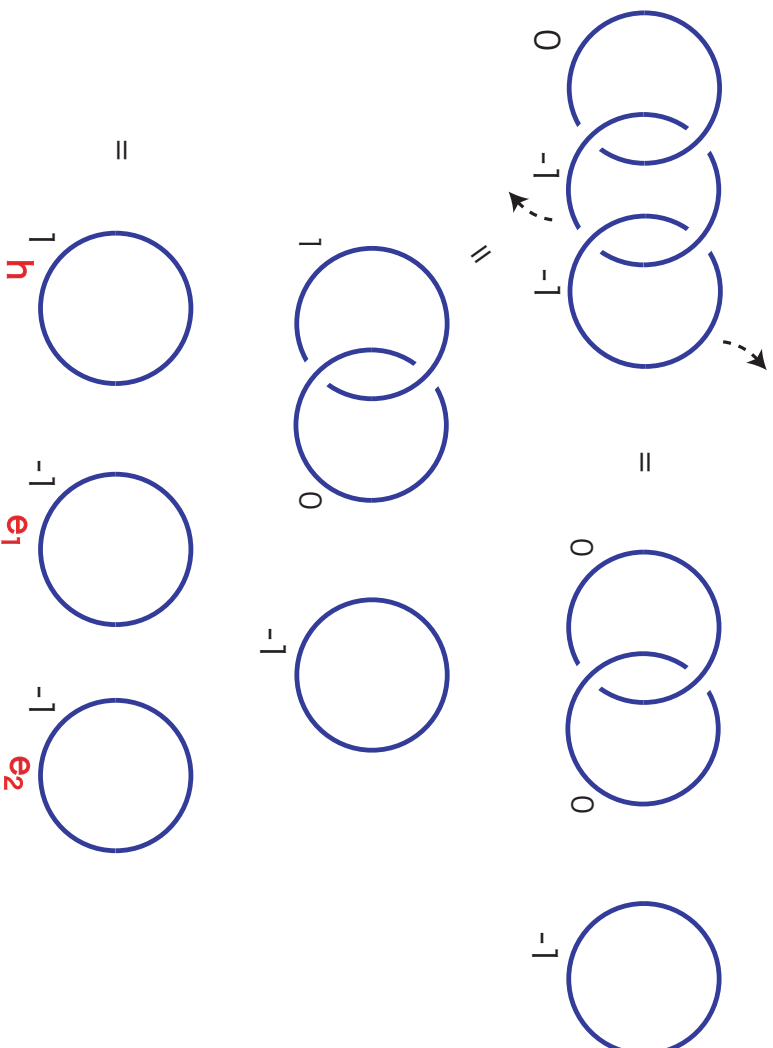


Figure 2-6 :

$$\begin{aligned}
 H_2(\mathbf{C}P^2 \# \overline{\mathbf{C}P^2} \# \overline{\mathbf{C}P^2}; \mathbf{Z}) &= H_2(\mathbf{C}P^2; \mathbf{Z}) \oplus H_2(\overline{\mathbf{C}P^2}; \mathbf{Z}) \oplus H_2(\overline{\mathbf{C}P^2}; \mathbf{Z}) \\
 &=: \mathbf{Z}h \oplus \mathbf{Z}e_1 \oplus \mathbf{Z}e_2.
 \end{aligned}$$

Exercise. $(S^2 \times S^2) \# \overline{\mathbf{C}P^2} \cong \mathbf{C}P^2 \# \overline{\mathbf{C}P^2} \# \overline{\mathbf{C}P^2} \cong (S^2 \tilde{\times} S^2) \# \overline{\mathbf{C}P^2}$

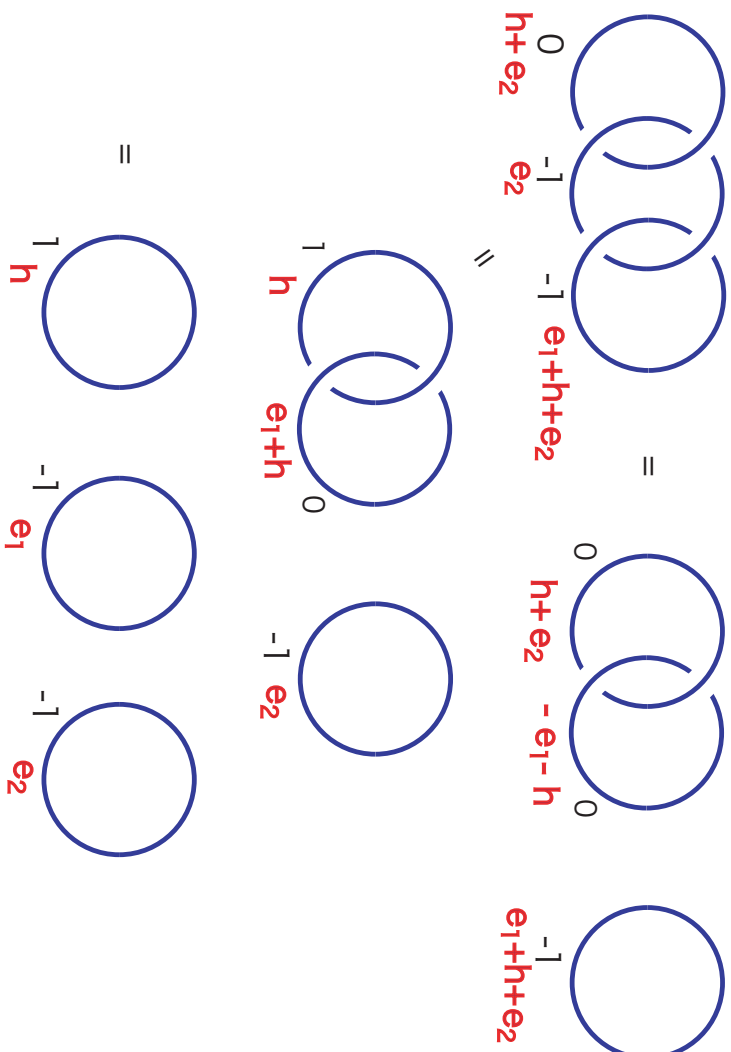


Figure 2-6':

In $(S^2 \times S^2) \# \overline{\mathbf{C}P^2}$, the class $[S^2 \times \{p}]$ is $h + e_2$, $[\{p\} \times S^2]$ is $-e_1 - h$.
the class $[\mathbf{C}P^1]$ in $\overline{\mathbf{C}P^2}$ is $h + e_1 + e_2$.

§3. 4-dim. with 1-handles

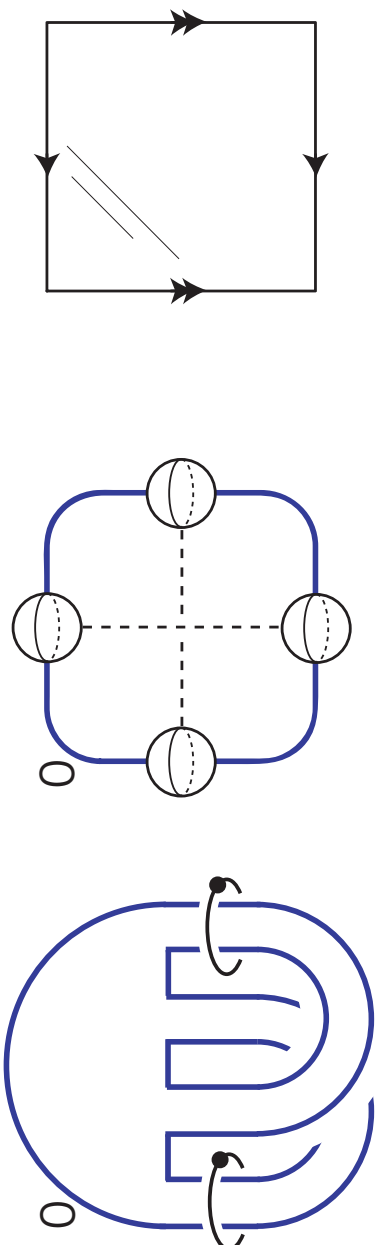


Figure 3-1 : $T^2 \times D^2$

§3. 4-dim. with 1-handles

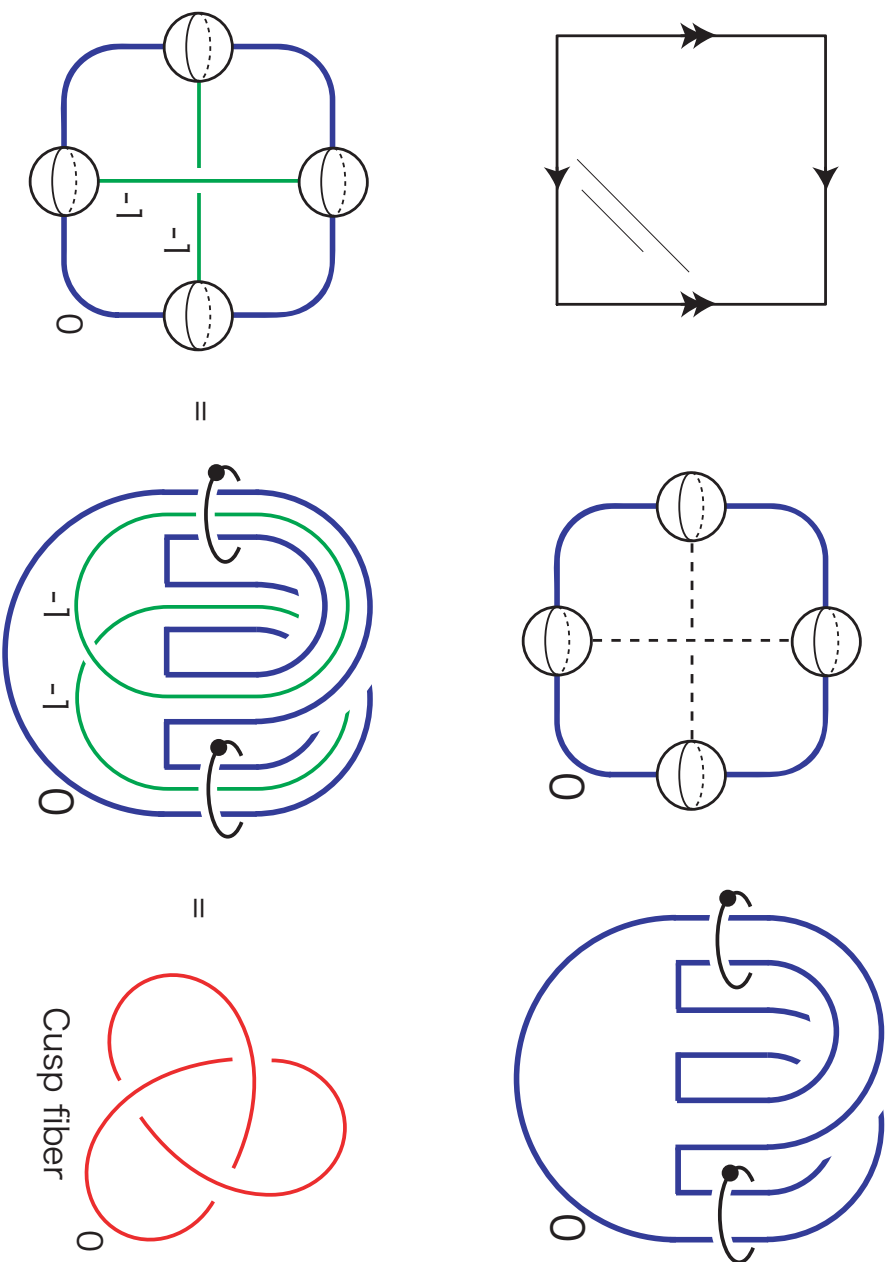


Figure 3-2 : The Cusp fiber

Mazur manifold is contractible, but Not a ball

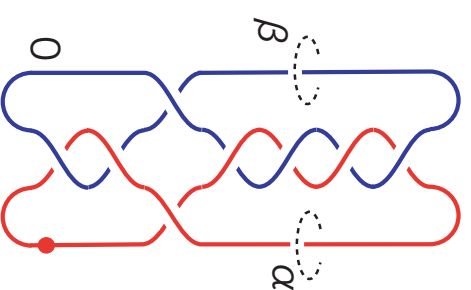
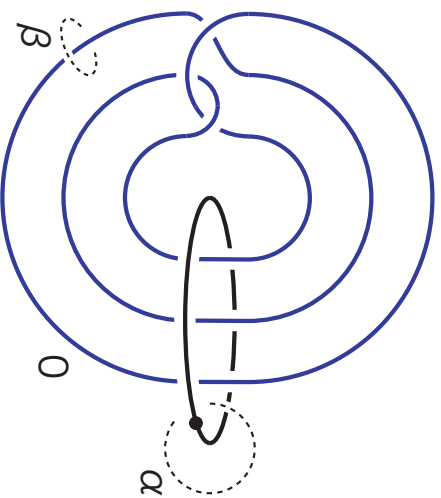
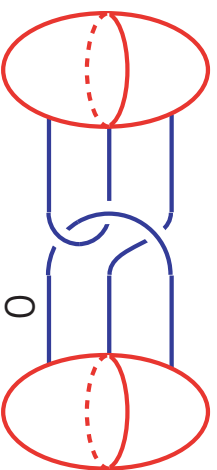


Figure 3-3 : Mazur manifold

Question.

- π_1 of this manifold?,
- boundary of it?,
- ...

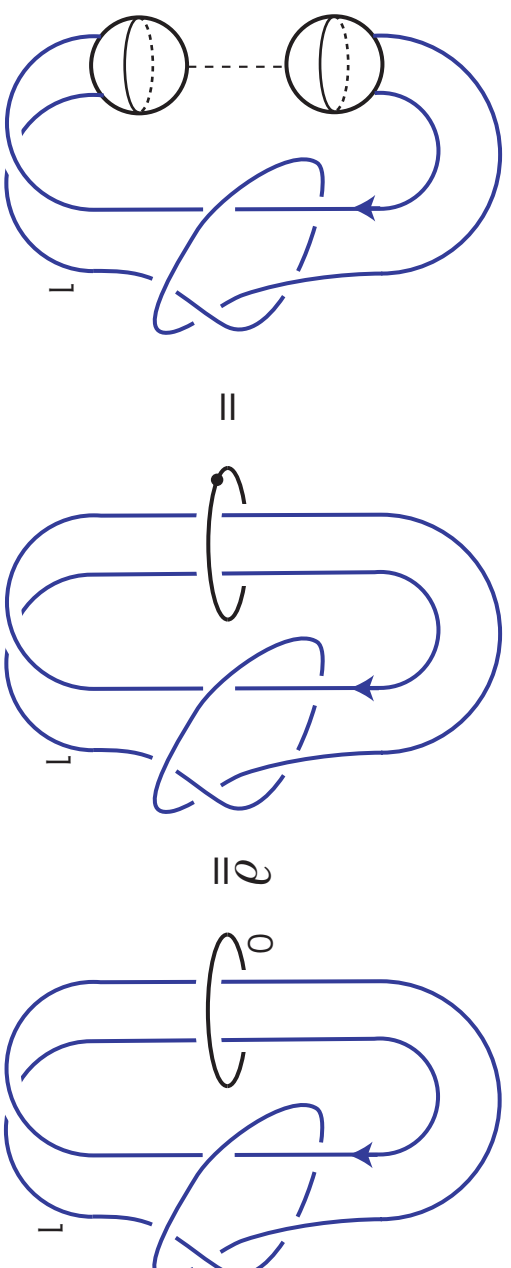


Figure 3-4 : a 4-manifold

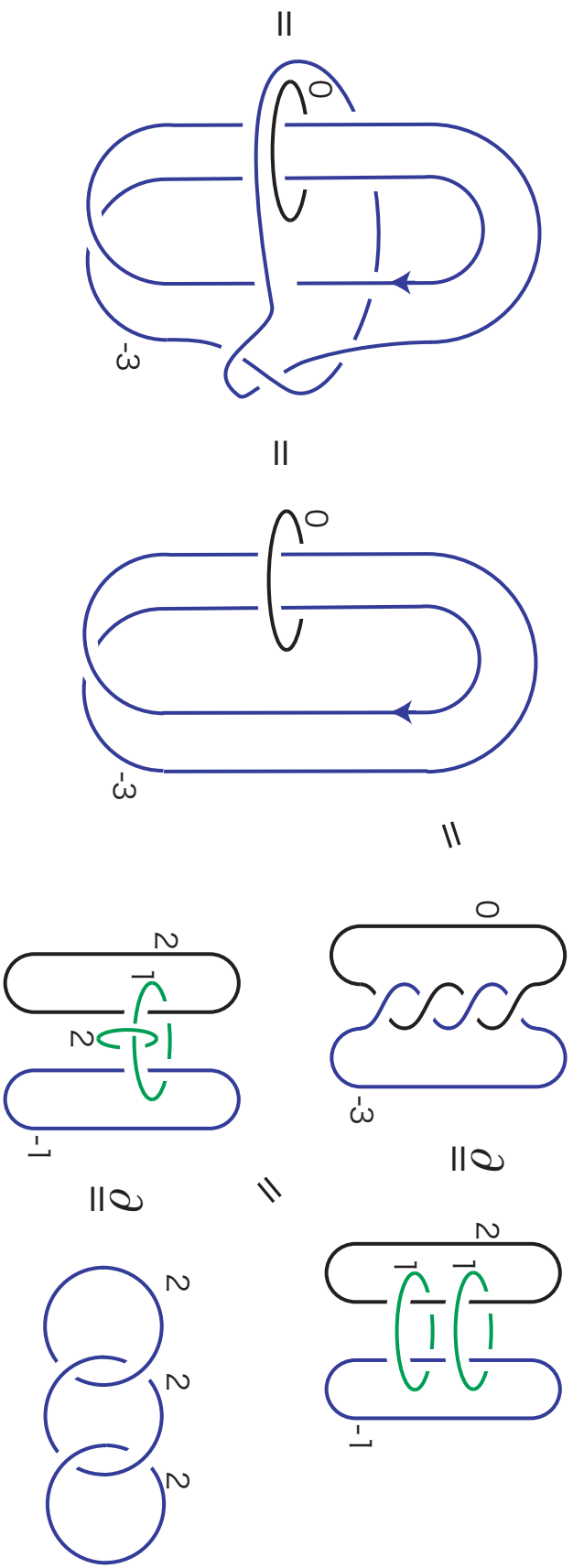
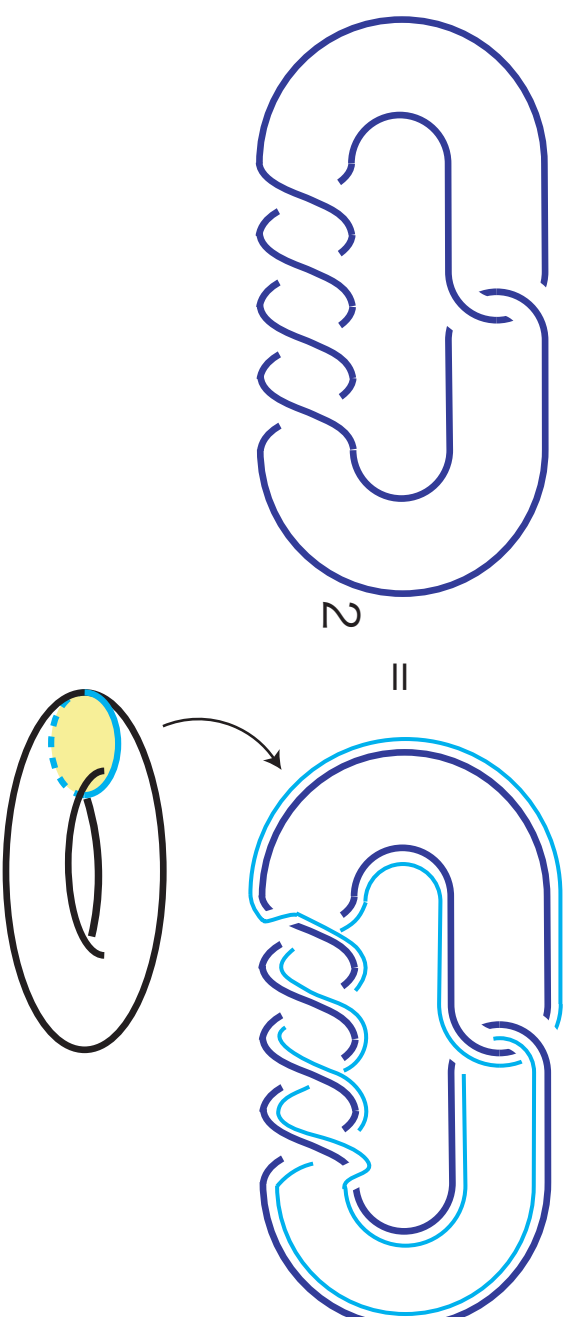


Figure 3-4(2) : the 4-manifold

is a \mathbf{Q} homology-ball whose $\pi_1 \cong \mathbf{Z}/2\mathbf{Z}$, and boundary is $L(4, 1)$.

§4. 3-dim. manifolds, Kirby Calculus

Dehn surgery coefficient = Framing = a parallel curve, or the linking number. *Remove and Reglue* Solid torus along each component such as “the meridian comes to the parallel”



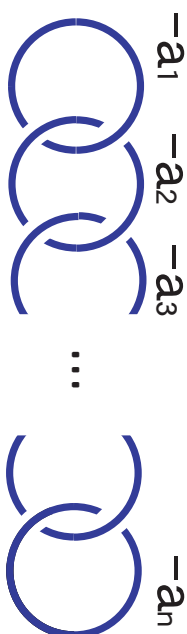
Thm. [Lickorish '62]

Any closed connected oriented 3-manifold is obtained by a framed link L in S^3 .

Notation: $M(L)$, or $(K; p)$.

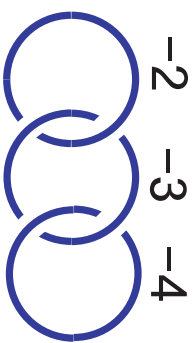
Framed Links for Lens $L(p, q)$

$$\frac{p}{q} = a_1 - \frac{1}{a_2 - \frac{1}{a_3 - \dots - \frac{1}{a_n}}} \quad (a_i > 1)$$

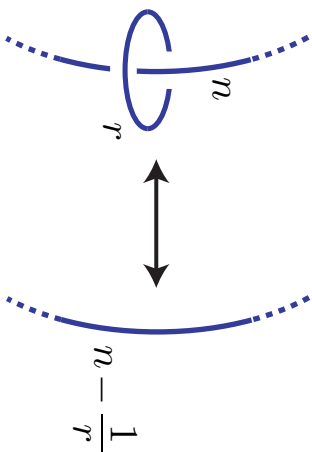


$L(18, 11)$ ($= L(18, 5)$)

$$\frac{18}{11} = 2 - \frac{1}{3 - \frac{1}{4}}, \quad \frac{18}{5} = 4 - \frac{1}{3 - \frac{1}{2}}$$



For $n \in \mathbf{Z}, r \in \mathbf{Q}$



ありがとうございました

最終日まで、じっくり過ごしましょう！